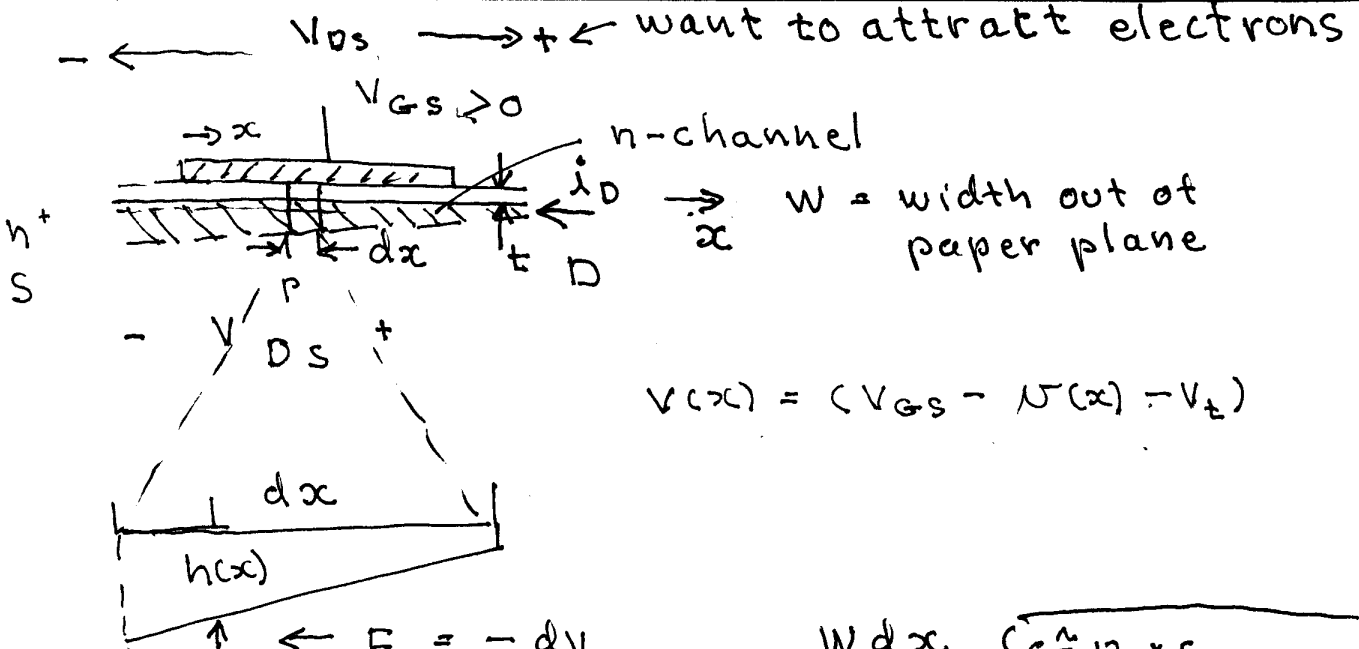


$E \quad E \quad I$



$dC = \frac{\epsilon d(\text{Area})}{t} = \frac{12 \times 9.85 \times 10^{-12} \text{ F/m} \cdot W dx}{t}$
 $C_{ox} = \frac{\epsilon}{t} \text{ [F/m}^2\text{]}$
 $dq = -(C_{ox} W dx) V(x)$ — called mobility (m^2/Vsec)
 $v = -\mu E_x = +\mu_n \frac{dV}{dx}$ — just frictional result since force = qE_x

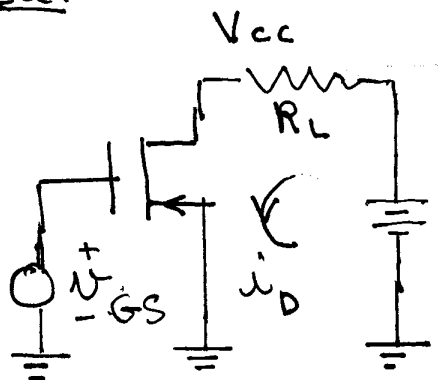
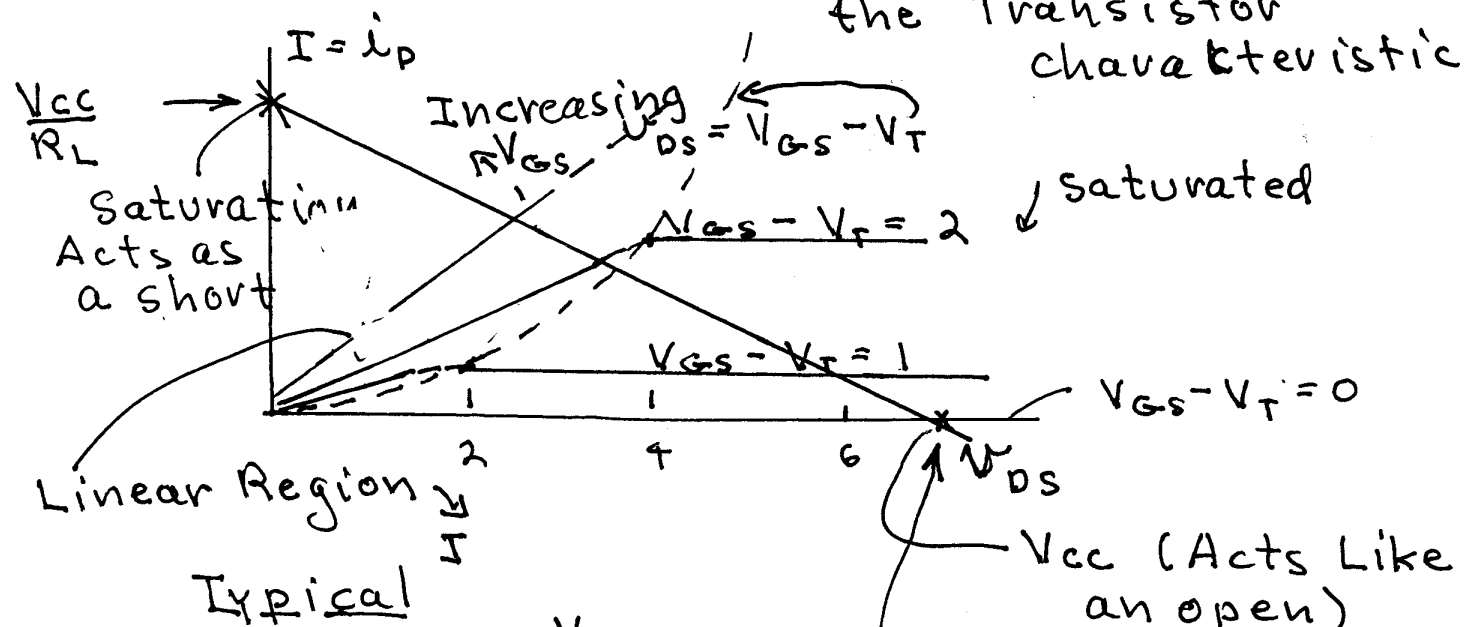
Current (Coul/sec) = $\frac{dq}{d\text{Volume}} \cdot \text{speed} = -C_{ox} W V(x) \mu_n \frac{dV}{dx}$
 $i_D = +C_{ox} W V(x) \mu_n \frac{dV}{dx} = \text{const}$ (same anywhere in channel)

Integrate to find $V(x)$ — Hambley = $2KL$
 $\int_0^L i_D dx = i_D L = +C_{ox} W \mu_n [(V_{GS} - V_T) V_{DS} - \frac{1}{2} V_{DS}^2]$

Saturation $V_{DS} = (V_{GS} - V_T)$ — defining curve
 Hambley = k_p
 $i_D = +C_{ox} \frac{W}{L} \mu_n \frac{1}{2} (V_{GS} - V_T)^2$

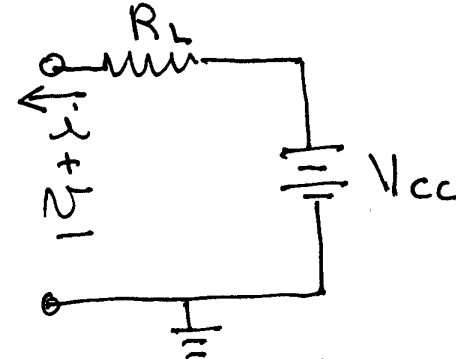
Linear Region $V_{DS} \ll (V_{GS} - V_T)$
 $i_D \approx +C_{ox} \frac{W}{L} \frac{\mu_n}{2} 2(V_{GS} - V_T) V_{DS}$ — Design Parameters
 Hambley's $K = \frac{W}{L} \frac{k_p}{2}$

Thevenin of Load on the Transistor characteristic



KVL
 $V_{DS} = -R_L i_D + V_{CC}$
 when $V_{DS} = 0$
 $i_D = \frac{V_{CC}}{R_L}$

The line, which is the Thevenin equivalent of the load circuit is called the "load line". Its simply this



The negative slope is simply the opposite reference for current

The solution approach is the same as for the diode but we can now "move" the solution with V_{GS}