UC Berkeley, EECS 100 Lab	LAB3: Sensor Interface	
NAME 1:	S	SID:
NAME 2:	S	SID:

## **Sensor Interfaces**

A very frequent scenario when designing electronic circuits: you need some sensory input, e.g. temperature. You found a sensor (e.g. a thermistor) that converts the actual temperature into an electrical voltage. The next step is to interface the sensor to the rest of your system, typically a computer (microcontroller). Figure 1 shows the setup.

Usually the output of the sensor is a small voltage in the milli- or micro-Volt range (for a full-scale signal), while the rest of the electronic system (e.g. the computer) expects much larger signals, typically around a Volt. For example, the scale we built earlier generated output signals that were only a few milli-Volt. To overcome this mismatch we need some kind of interface between the sensor and the computer (or whatever we would like to connect the sensor to), as illustrated in Figure 2 on the next page.

Sensor interfaces can perform many functions. Here we focus on the task of gaining up the signal to appropriate amplitude. Specifically, we want the interface to perform the function

$$v_2 = A_v v_1 \tag{1}$$

where  $A_v$  is the voltage gain. For example, if  $A_v = 21$  and  $v_1 = 7.2$  mV,  $v_2 = 0$ 

We will build the sensor interface out of operational amplifiers. To test it, we need an input, and something to verify the output. We could use the scale constructed in an earlier lab for the input, but this would require us to wire up that circuit again. Moreover, if we encounter problems, we would have to determine if they are due to the interface or the sensor—not always a trivial issue.

A better solution is to synthesize an appropriate input  $v_1$  with reliable and well characterized (that's why it's expensive) laboratory equipment to test our amplifier circuit. Once we are satisfied with the result we can combine building blocks (and test again). Tackling circuits one-by-one in this fashion significantly simplifies our task and speeds up our work.

We will use the signal generator to simulate the transducer and the oscilloscope to verify the output from our sensor interface.

## Signal Generator and Oscilloscope

Download the manuals for the oscilloscope and signal generator and read the quick start and overview guides. Program the signal generator to produce a 1 kHz sinewave with  $V_s = 2.1$  V zero-to-peak amplitude. Connect the signal generator to the oscilloscope as shown in Figure 3 on the following page. Observe the sinewave on the oscilloscope display. What is the zero-to-peak amplitude?



If you just cannot get this right, reread the guide for the function generator. Feel free to play in the lab with different settings of the function generator, e.g. higher frequency signals. Even test equipment is not "ideal" when used outside its specifications (which the manual explains, although in rather technical terms).



Figure 1 Sensor connected to an electronic system (e.g. a computer).

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# **Operational Amplifier**

Let's check out the operational amplifier before designing a more complex circuit. This way we are sure the part is working and we get all connections right (e.g. supplies!) without wasting a lot of time debugging a complex setup.

Download the datasheet of the LMC6482M/AM operational amplifier. We are using the part in a 8-pin dual-in-line package. Find the following specifications from the datasheet:

Pin number of the positive supply,  $V^+$ Maximum supply voltage,  $V^+ - V^-$ Minimum supply voltage,  $V^+$ Maximum input current,  $I_B$ Minimum junction temperature,  $T_j$  [C] Maximum junction temperature,  $T_j$  [C] Minimum large signal voltage gain  $A_v$ , sourcing into  $R_L = 2 \, k \Omega$ ,  $V^+$  (unitless)

	1 pt.
	2
	1 pt.
	3
	1 pt.
	4
	1 pt.
	5
	1 pt.
	6
	1 pt.
	7
	1 pt.
	8

Now that we know the pinout of the operational amplifier chip, we can connect it to a power supply and an input to see how it reacts in various circumstances. The input will come from the function generator, and will have values above and below ground. In order to amplify negative signals, the amplifier will need a negative voltage supply, as the output cannot fall below the minimum supplied voltage. Also, the sum of the supply voltages must not exceed the chip's maximum supply voltage. Use 5 volts for *Vdd* and *Vss* unless otherwise directed.



Draw the openloop  $V_{out}$  versus  $V_{in}$  characteristic of the operational amplifier.

Draw the expected  $V_{out}$  versus  $V_{in}$  characteristics on the plot.

Turn on the oscilloscope.

Change the scope to XY mode by pressing the Main/Delayed button followed by the XY soft key. Set the function generator to sine wave output at 10 Hz with 100mV peak to peak amplitude.

Label the axes (variable, units, ticks) in the graph below and show the measured result in a different color than the expected result.



Most practical opamp circuits use feedback to set the gain to an accurate and reasonable (e.g. 10) value. This works very well – provided that the feedback is connected correctly. Here we compare opamps with positive and negative feedback.



Build the negative feedback circuit and generate the XY plot just as you did in 'y g'rcuvpart0 Copy your measured results to the plot below.

Repeat all above with a positive feedback circuit.

Explain what's happening and summarize your result in the graph.



Figure 4 shows the circuit diagram for an inverting amplifier based on the LMC6482. The inputs of the unused opamp OP2 are grounded, a good precautionary measure that prevents the part from accidentally turning on or even oscillate and interfere with other devices.

Signals are often bipolar (i.e. can assume both positive and negative voltage values). Since the amplifier output cannot possibly swing below the supply, both positive and negative supply voltages  $V_{dd}$  and  $V_{ss}$  are needed, as indicated in the diagram. To avoid clutter, the supplies are usually omitted from the circuit diagram. Do not forget to connect them in practice, as the circuit will obviously not work without.

Mark the pin numbers for all connections in the diagram and build your circuit on a protoboard. Verify all connections before applying power. If the part gets hot, check if the supply is backwards. Choose  $V_{dd} = V_{ss} = 5 \text{ V}$ ,  $R_1 = 1 \text{ k}\Omega$  and  $R_2$  such that  $v_o/v_i = -10$ .



Figure 4 Inverting amplifier circuit diagram.

Program the function generator for a sinusoidal output at 1 kHz and 200 mV zero to peak amplitude. Using the oscilloscope, verify that  $v_o/v_i = -10$ . This is most easily accomplished by setting the input of the oscilloscope for the channel displaying  $v_o$  to inverting and its gain to half that of the other channel. Then adjust the vertical position such that the two outputs coincide.

Experiment with other inputs (increased signal amplitude, frequency, and different waveforms). Summarize your observations:

Show your setup to the assistant.

### **Audio Amplifier**

Now you are ready to design a sensor interface. We also connect a speaker to the output so we can listen to the output in addition to examining it with the oscilloscope (Figure 5 on the following page). We use the function generator to "simulate" the sensor as before, but add an adjustable  $100 \text{ k}\Omega$  resistor (potentiometer) in series with its output to mimic the often high and varying output resistance of practical sensors.

Capacitor  $C_1$  blocks direct current from passing through the speaker, preventing it or the amplifier from overheating. Do not worry if you are not familiar with capacitors, they will be covered in a later lab. Just build the circuit exactly as shown in the diagram, paying special attention to polarities. If the capacitor explodes (they really do this), you have connected it incorrectly. You have been warned!

Your objective for designing the sensor interface is for the gain  $Av = v_3/v_1 = 8$  regardless of the setting of potentiometer  $P_1$ , i.e. the resistance of  $P_1$  can be set to any value between  $0 \Omega$  and  $100 \text{ k}\Omega$  without  $A_v$  changing. For this to be possible, you need to design the sensor interface such that its input current  $i_1$  is (virtually) zero. Some amplifier configurations have this property, others do not. Select an appropriate one. Draw the circuit diagram in the space below. Include all component values and indicate all supplies their values. Mark pin numbers for operational amplifiers in your diagram.

Use the LMC6482 for your design. It is not optimal for this purpose since it cannot drive low impedance loads and hence needs the 100  $\Omega$  series resistor (standard speakers are  $\approx 8 \Omega$ ). Add an output stage (e.g. LM386 or LM4951) to get increased volume.



Figure 5 Sensor interface with audio output.

6 pts. 10

Verify your circuit, initially setting the function generator to a 440 Hz sinusoidal output with amplitude 0.5 V. Check that  $v_2$  and  $v_3$  are undistorted sine waves (disconnect the speaker to investigate any problems you might have). Then verify that the amplitudes of  $v_2$  and  $v_3$  are independent of the setting of the potentiometer (make sure it's connected correctly as shown in the diagram).

Now check different waveforms. Can you hear the difference between 440 Hz and 880 Hz? What about 10 kHz? Square- and sawtooth waveforms? At very low frequencies you may be able to see the membrane of the speaker vibrate, especially if you put a light weight (paper clip or corn of rice) on top.

Demonstrate your circuit to the assistant and show that the output amplitude is independent of the potentiometer setting.

#### LAB3: Sensor Interface

LAB TIME:

NAME:

SID:

Copy your results from the blue Prelab boxes in the rest of the lab onto this page and turn it in at the beginning of the lab section. Only the values on this page will count!

Blue box #	Result	Points
0		_/ 1
1		_/ 1
2		_/ 1
3		/ 1
4		/ 1
5		/ 1
6		/ 1
7		/ 1
8		/ 1
9		/ 1