

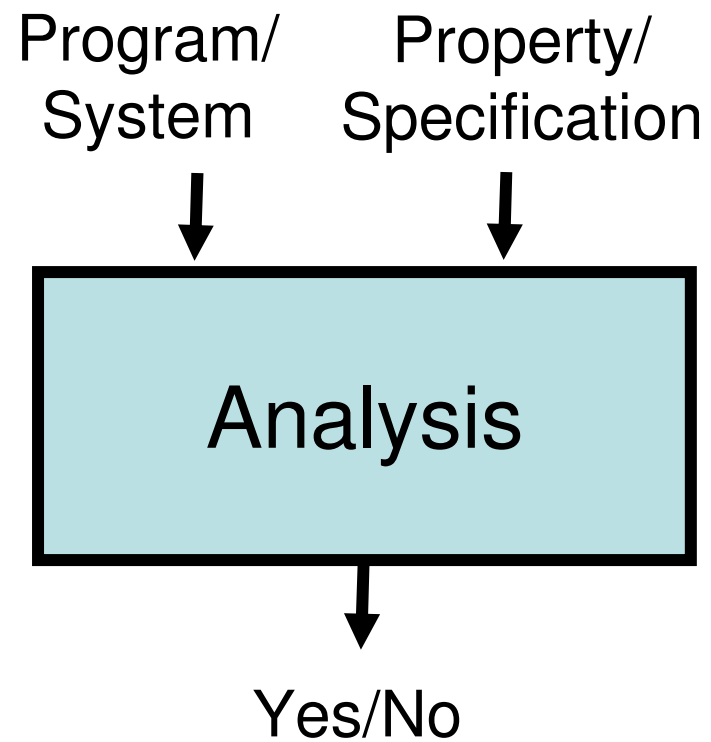
From Boolean to Quantitative System Specifications

Tom Henzinger
EPFL

Outline

- 1 The Quantitative Agenda
- 2 Some Basic Open Problems
- 3 Some Promising Directions

The Boolean Agenda



The Boolean Agenda

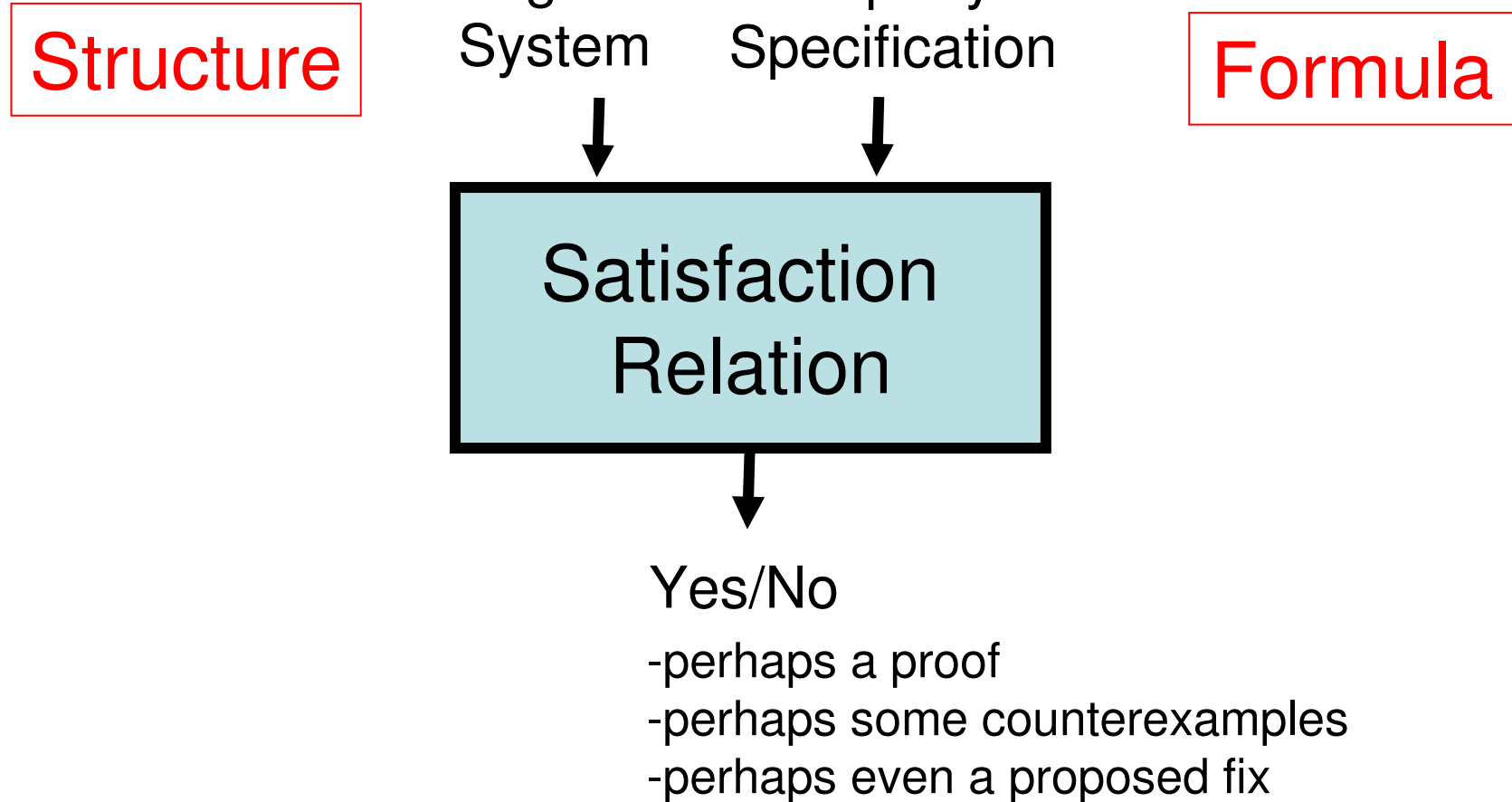
Program/
System Property/
 Specification



Yes/No

- perhaps a proof
- perhaps some counterexamples
- perhaps even a proposed fix

The Boolean Agenda



The Boolean Agenda

Transition
system.

Program/
System

Property/
Specification

Every request is
followed by a grant.



Yes/No

- perhaps a proof
- perhaps some counterexamples
- perhaps even a proposed fix

The Boolean Agenda

Timed
automaton.

Quantitative
Program/
System

Quantitative
Property/
Specification

Every request is
followed by a grant
within 5 time units.



Yes/No

- perhaps a proof
- perhaps some counterexamples
- perhaps even a proposed fix

The Boolean Agenda

Markov
process.

Quantitative
Program/
System

Quantitative
Property/
Specification

Every request is
followed by a grant
within probability $1/2$.



Yes/No

- perhaps a proof
- perhaps some counterexamples
- perhaps even a proposed fix

The Boolean Agenda

Markov
process.

Quantitative
Program/
System

Quantitative
Property/
Specification

Every request is
followed by a grant
within probability $1/2$.

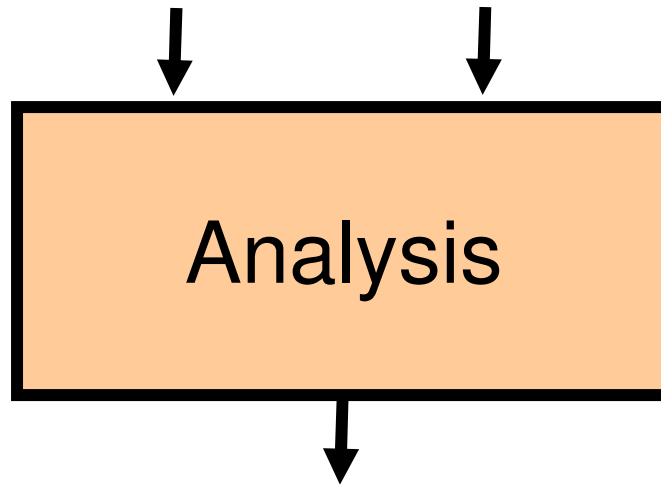


IB

- perhaps a proof
- perhaps some counterexamples
- perhaps even a proposed fix

The Quantitative Agenda

Quantitative Program/
System Quantitative Property/
Specification



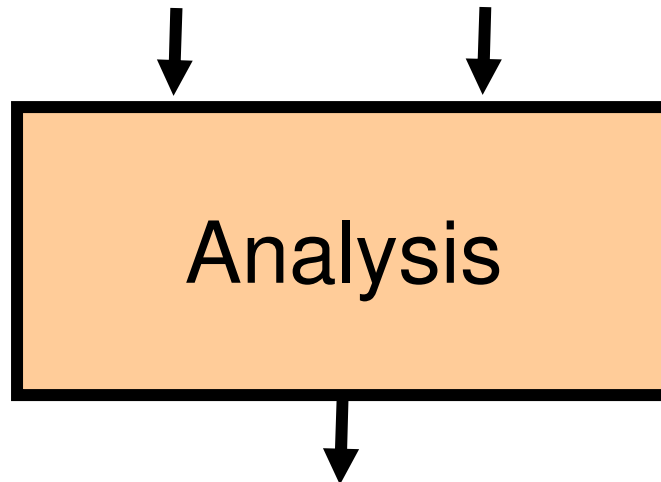
\mathbb{R}

-measure of “fit” between system and spec
-could be cost, quality, etc.

The Quantitative Agenda

Quantitative Program/
System ~~Quantitative~~ Property/
Specification

Every request is followed by a grant.



The less time between requests and grants, the better.

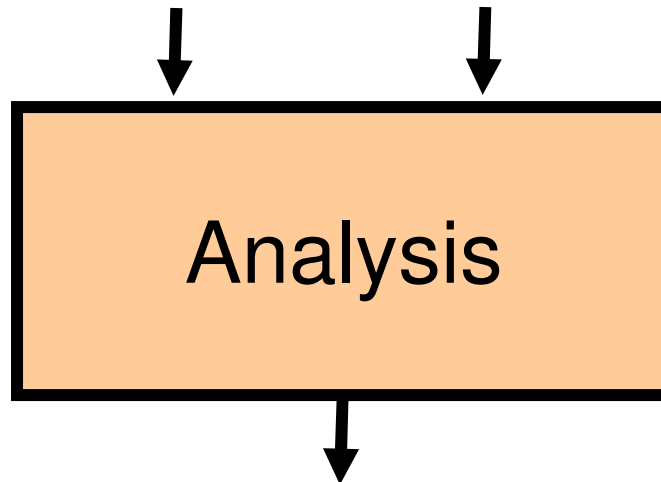
R

-measure of “fit” between system and spec
-could be cost, quality, etc.

The Quantitative Agenda

~~Quantitative~~ Program/
System ~~Quantitative~~ Property/
Specification

Every request is
followed by a grant.



The fewer unnecessary
grants, the better.

\mathbb{R}

-measure of “fit” between system and spec
-could be cost, quality, etc.

The Quantitative Agenda

Q1 Assigning values to behaviors

Boolean case: correct vs. incorrect behaviors

Q2 Assigning values to systems/properties

Boolean case: sets of behaviors (nondeterminism)

Q3 Assigning values to pairs of systems

Boolean case: preorders on systems

Q1 Assigning Values To Behaviors

a. Probabilities

b. Resource use

- worst case vs. average case (e.g. response time, QoS)
- peak vs. accumulative (e.g. power consumption)

c. Quality measures

- discounting vs. long-run averaging (e.g. reliability)

Q1 Assigning Values To Behaviors

a: ok

b: fail

Discounted value ($0 < d < 1$):

aaaaaaaaaa...	1
aaaaaaaaab...	$1 - d^8$
aab...	$1 - d^3$
b...	0

Long-run average value:

aaaaaaaaaa...	1
aaabaaabaaab...	$1 - \frac{1}{4}$
abaabaaab...	0

Q2

Assigning Values To Systems

x: behaviors

w: observations

A,B: systems

$$A(w) = \sup_x \{ \text{val}(x) : \text{obs}(x) = w \} \quad ?$$

$$B(w) = \exp_x \{ \text{val}(x) : \text{obs}(x) = w \} \quad ??$$

Q2, Q3 Assigning Values To Systems

x: behaviors

w: observations

A,B: systems

$$A(w) = \sup_x \{ \text{val}(x) : \text{obs}(x) = w \} \quad ?$$

$$B(w) = \exp_x \{ \text{val}(x) : \text{obs}(x) = w \} \quad ??$$

$$\text{diff}(A,B) = \sup_w \{ |A(w) - B(w)| \} \quad ???$$

Compositionality: $\text{diff}(A||B,A'||B) \leq f(\text{diff}(A,A'))$ [AFHMS].

Is there a Quantitative Framework with

- an appealing mathematical formulation,
- useful expressive power, and
- good algorithmic properties?

(Like the boolean theory of ω -regularity.)

Outline

- 1 The Quantitative Agenda
- 2 Some Basic Open Problems
- 3 Some Promising Directions

Property = Language

Alphabet:

Σ

$\Sigma = \{a,b,c\}$

Language:

$L \subseteq \Sigma^\omega$

$L = (a^+b)^+(a^\omega \cup c^\omega) \cup (a^+b)^\omega$

$abaabaaabcccccc... \in L$

$abcabc... \notin L$

Boolean Language

Alphabet:

Σ

$\Sigma = \{a,b,c\}$

Language:

$L \subseteq \Sigma^\omega$

$L = (a^+b)^+(a^\omega \cup c^\omega) \cup (a^+b)^\omega$

$abaabaaabcccc... \in L$

$abcabc... \notin L$

$L: \Sigma^\omega \rightarrow \mathbb{B}$

Specification = Automaton

Q

states

$\lambda: Q \rightarrow \Sigma$

labeling

$q_0 \in Q$

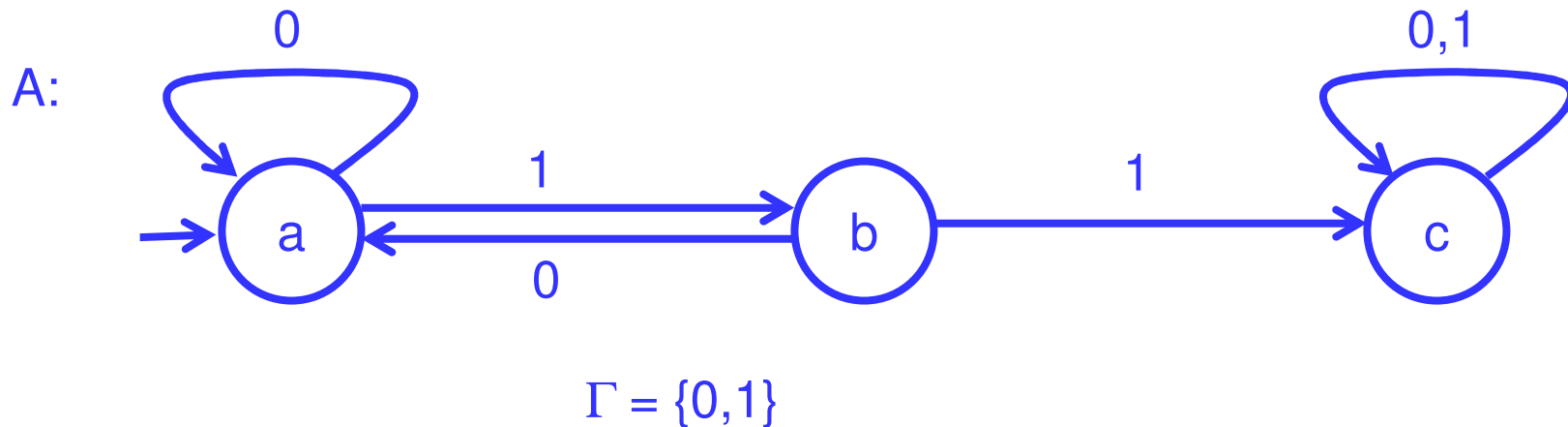
initial state

Γ

choices

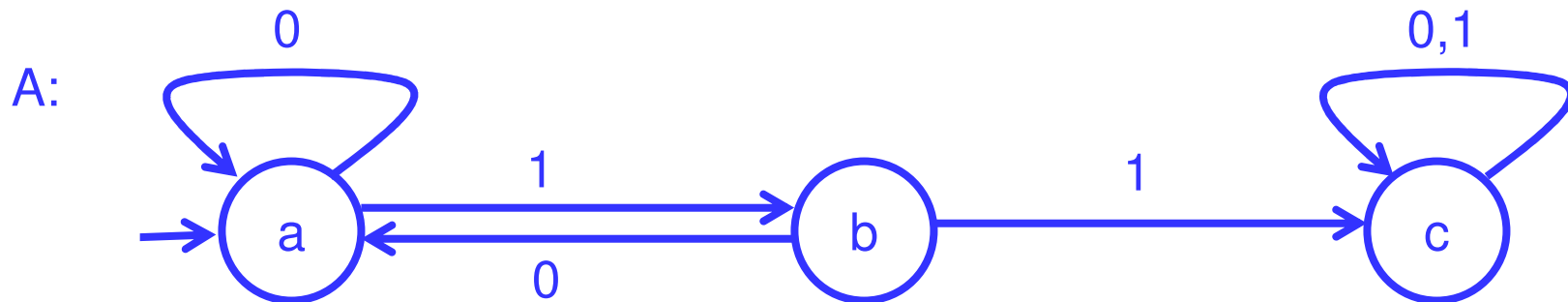
$\delta: Q \times \Gamma \rightarrow Q$

transition function



Specification = Automaton

Q	states
$\lambda: Q \rightarrow \Sigma$	labeling
$q_0 \in Q$	initial state
Γ	choices
$\delta: Q \times \Gamma \rightarrow Q$	transition function

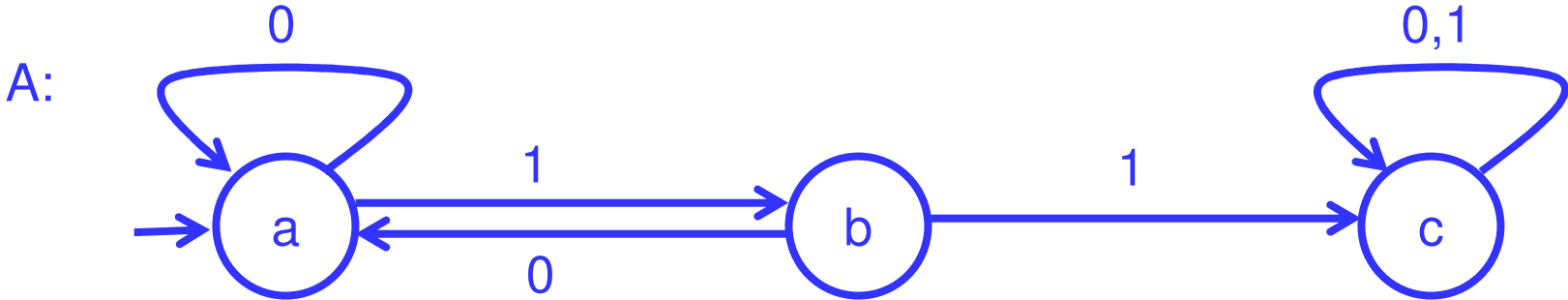


$$\Gamma = \{0,1\}$$

$$L(A) = (a+b)^+(a^\omega \cup c^\omega) \cup (a+b)^\omega$$

Automaton

Q	states
$\lambda: Q \rightarrow \Sigma$	labeling
$q_0 \in Q$	initial state
Γ	choices
$\delta: Q \times \Gamma \rightarrow Q$	transition function



“scheduler”

0101111... → aababccc...

“outcome”

Automaton

Q	states
$\lambda: Q \rightarrow \Sigma$	labeling
$q_0 \in Q$	initial state
Γ	choices
$\delta: Q \times \Gamma \rightarrow Q$	transition function

Scheduler: $x: Q^+ \rightarrow \Gamma$
S ... set of schedulers

Outcome: $f(x) = q_0q_1q_2 \dots$
where $\forall i : q_{i+1} = \delta(q_i, x(q_0 \dots q_i))$

Language: $L = \{ \lambda(f(x)) : x \in S \}$

Automaton

Q	states
$\lambda: Q \rightarrow \Sigma$	labeling
$q_0 \in Q$	initial state
Γ	choices
$\delta: Q \times \Gamma \rightarrow Q$	transition function

Scheduler: $x: Q^+ \rightarrow \Gamma$
 S ... set of schedulers

Outcome: $f(x) = q_0q_1q_2 \dots$
where $\forall i : q_{i+1} = \delta(q_i, x(q_0 \dots q_i))$

Language: $L = \{ \lambda(f(x)) : x \in S \}$
 $L(w) = \sup\{ f(x) : x \in S \text{ s.t. } \lambda(f(x)) = w \}$

Language Inclusion

Given two automata A and B , is $L(A) \subseteq L(B)$?

i.e. $\forall w \in \Sigma^\omega : L(A)(w) \leq L(B)(w)$

Satisfaction = Language Inclusion

Given two automata A and B , is $L(A) \subseteq L(B)$?

i.e. $\forall w \in \Sigma^\omega : L(A)(w) \leq L(B)(w)$

For finite automata, PSPACE-complete.

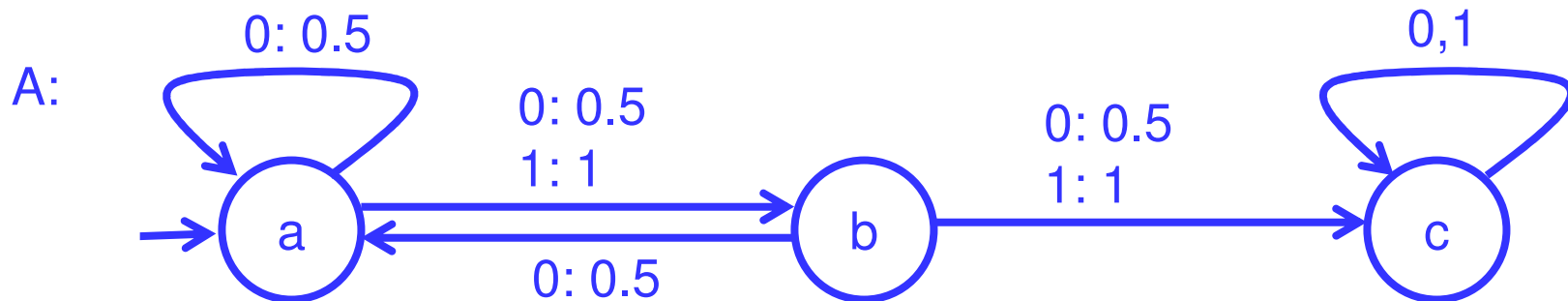
Probabilistic Language

Word:	element of Σ^ω
Probabilistic Word:	probability space on Σ^ω
Probabilistic Language:	set of probabilistic words

w: $ab\Sigma^\omega \rightarrow 1/2$
 $aab\Sigma^\omega \rightarrow 1/4$
 $aaab\Sigma^\omega \rightarrow 1/8$
 ...

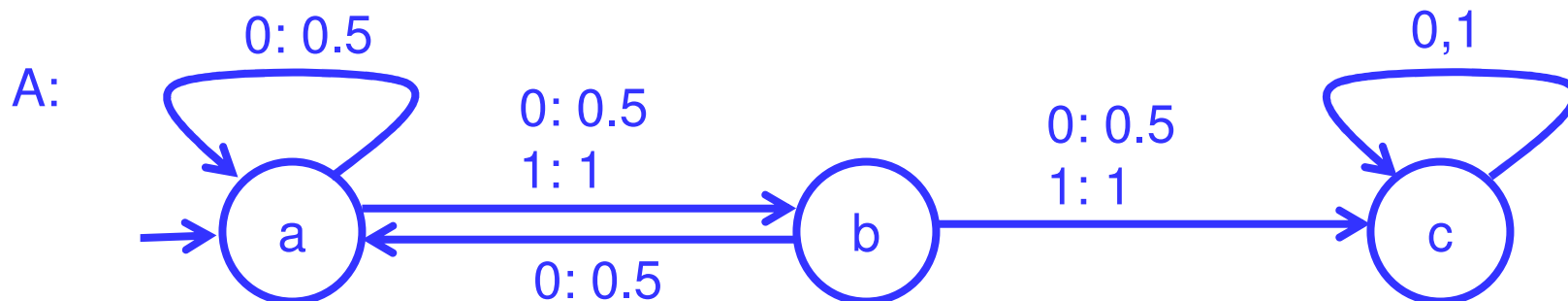
Markov Decision Process

Q	states
$\lambda: Q \rightarrow \Sigma$	labeling
$q_0 \in Q$	initial state
Γ	choices
$\delta: Q \times \Gamma \rightarrow D(Q)$	transition function



Markov Decision Process

Q	states
$\lambda: Q \rightarrow \Sigma$	labeling
$q_0 \in Q$	initial state
Γ	choices
$\delta: Q \times \Gamma \rightarrow D(Q)$	transition function



0101111... \rightarrow abccc... \rightarrow 1/2
aabccc... \rightarrow 1/4
...

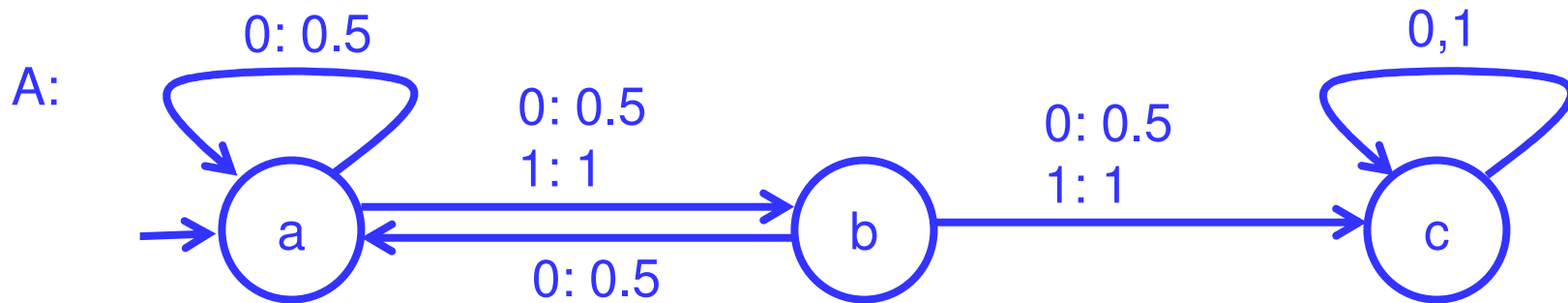
Markov Decision Process

Q	states
$\lambda: Q \rightarrow \Sigma$	labeling
$q_0 \in Q$	initial state
Γ	choices
$\delta: Q \times \Gamma \rightarrow D(Q)$	transition function

Pure scheduler:	$x: Q^+ \rightarrow \Gamma$
Probabilistic scheduler:	$x: Q^+ \rightarrow D(\Gamma)$

Markov Decision Process

Q	states
$\lambda: Q \rightarrow \Sigma$	labeling
$q_0 \in Q$	initial state
Γ	choices
$\delta: Q \times \Gamma \rightarrow D(Q)$	transition function



$\{0: 0.5, 1: 0.5\}^\omega \rightarrow$

$abccc\dots$	\rightarrow	$9/16$
$aabccc\dots$	\rightarrow	$9/64$
\dots		

Probabilistic Language Inclusion

Given two MDPs A and B , is $L(A) \subseteq L(B)$?

Probabilistic Language Inclusion

Given two MDPs A and B , is $L(A) \subseteq L(B)$?



Probabilistic Language Inclusion

Given two MDPs A and B , is $L(A) \subseteq L(B)$?

?

Open even if specification B is deterministic (i.e. $|\Gamma| = 1$) and implementation scheduler required to be pure.

If both sides are deterministic, then it can be solved in polynomial time (equivalence of Rabin's probabilistic automata) [Tzeng, DHR].

Quantitative Language

Language: $L: \Sigma^\omega \rightarrow \mathbb{B}$

Quantitative Language: $L: \Sigma^\omega \rightarrow \mathbb{R}$

$$L(ab^\omega) = 1/2$$

$$L(aab^\omega) = 1/4$$

$$L(aaab^\omega) = 1/8$$

...

Weighted Automaton

Q

states

$\lambda: Q \rightarrow \Sigma$

labeling

$q_0 \in Q$

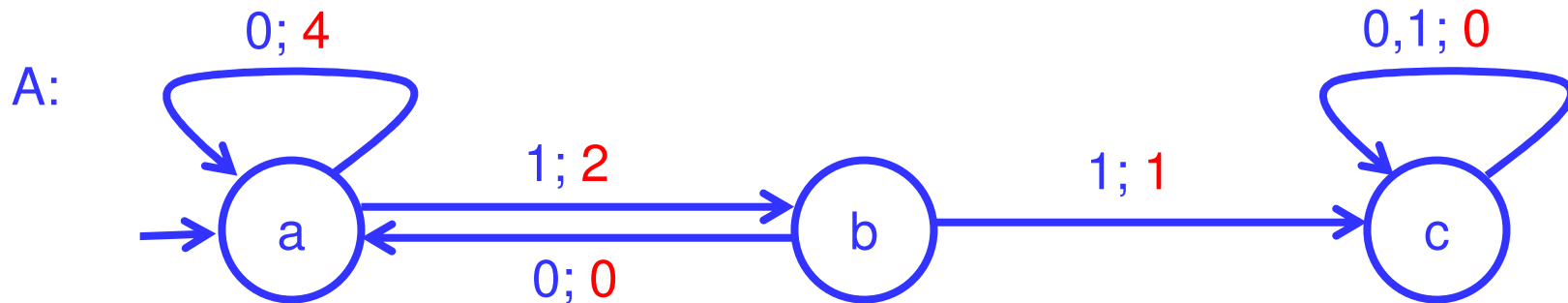
initial state

Γ

choices

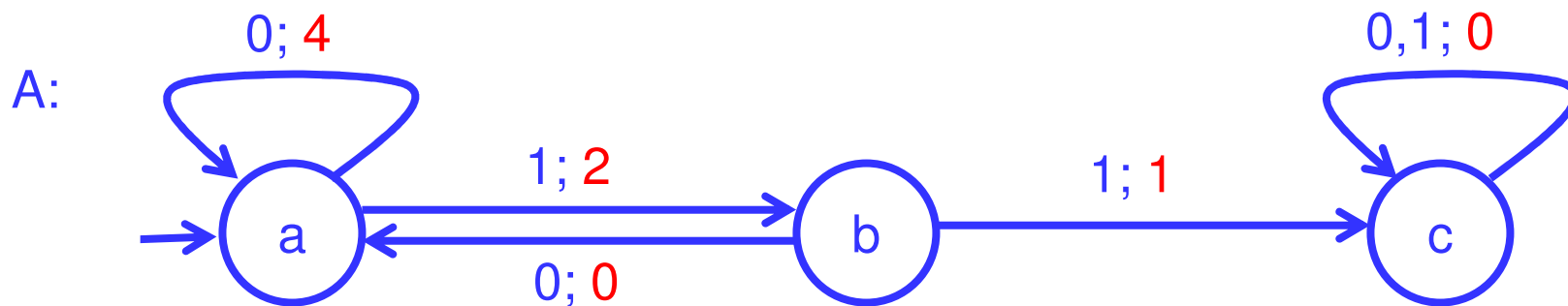
$\delta: Q \times \Gamma \rightarrow \mathbb{R} \times Q$

transition function



Weighted Automaton

Q	states
$\lambda: Q \rightarrow \Sigma$	labeling
$q_0 \in Q$	initial state
Γ	choices
$\delta: Q \times \Gamma \rightarrow \mathbb{R} \times Q$	transition function



Max value: 0101111... \rightarrow aababccc...; 4
 1111111... \rightarrow abccc...; 2

Weighted Automaton

Q	states
$\lambda: Q \rightarrow \Sigma$	labeling
$q_0 \in Q$	initial state
Γ	choices
$\delta: Q \times \Gamma \rightarrow \mathbb{R} \times Q$	transition function

Outcome: $f(x) = q_0 v_1 q_1 v_2 q_2 \dots$
where $\forall i : (v_{i+1}, q_{i+1}) = \delta(q_i, x(q_0 \dots q_i))$

Max value: $\text{val}(q_0 v_1 q_1 v_2 q_2 \dots) = \sup\{ v_i : i \geq 1 \}$

Weighted Automaton

Q	states
$\lambda: Q \rightarrow \Sigma$	labeling
$q_0 \in Q$	initial state
Γ	choices
$\delta: Q \times \Gamma \rightarrow \mathbb{R} \times Q$	transition function

Outcome: $f(x) = q_0 v_1 q_1 v_2 q_2 \dots$
where $\forall i : (v_{i+1}, q_{i+1}) = \delta(q_i, x(q_0 \dots q_i))$

Max value: $\text{val}(q_0 v_1 q_1 v_2 q_2 \dots) = \sup\{ v_i : i \geq 1 \}$

q-Language: $L(w) = \sup\{ \text{val}(f(x)) : x \in S \text{ s.t. } \lambda(f(x)) = w \}$

Different Value Functions

Max value: $\text{val}(q_0 v_1 q_1 v_2 q_2 \dots) = \sup\{ v_i : i \geq 1 \}$
(only 0 and 1 costs: finite automaton)

Limsup value: $\text{val} = \lim_{n \rightarrow \infty} \sup\{ v_i : i \geq n \}$
(only 0 and 1 costs: Buechi automaton)

Different Value Functions

Max value: $\text{val}(q_0 v_1 q_1 v_2 q_2 \dots) = \sup\{ v_i : i \geq 1 \}$
(only 0 and 1 costs: finite automaton)

Limsup value: $\text{val} = \lim_{n \rightarrow \infty} \sup\{ v_i : i \geq n \}$
(only 0 and 1 costs: Buechi automaton)

Limavg value: $\text{val} = \lim_{n \rightarrow \infty} 1/n \cdot \sum_{1 \leq i \leq n} v_i$

Different Value Functions

Max value: $\text{val}(q_0 v_1 q_1 v_2 q_2 \dots) = \sup\{ v_i : i \geq 1 \}$
(only 0 and 1 costs: finite automaton)

Limsup value: $\text{val} = \lim_{n \rightarrow \infty} \sup\{ v_i : i \geq n \}$
(only 0 and 1 costs: Buechi automaton)

Limavg value: $\text{val} = \lim_{n \rightarrow \infty} 1/n \cdot \sum_{1 \leq i \leq n} v_i$

Discounted: $\text{val} = \sum_{i \geq 1} d^i \cdot v_i$ for some $0 < d < 1$

Quantitative Language Inclusion

Given two cost automata A and B, is
 $\forall w \in \Sigma^\omega : L(A)(w) \leq L(B)(w) ?$

Quantitative Language Inclusion

Given two cost automata A and B, is
 $\forall w \in \Sigma^\omega : L(A)(w) \leq L(B)(w) ?$

For max and limsup values: PSPACE.

For limavg and discounted values: Open.

Quantitative Language Inclusion

Given two cost automata A and B, is
 $\forall w \in \Sigma^\omega : L(A)(w) \leq L(B)(w) ?$

For max and limsup values: PSPACE.

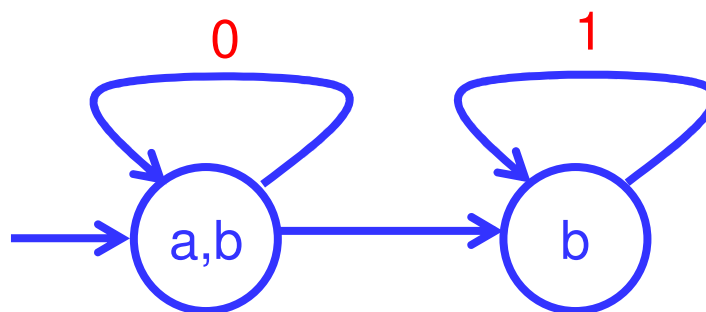
For limavg and discounted values: Open.

If specification B is deterministic,
then it can be solved in polynomial time [CDH].

Expressiveness [CDH]

E.g. LimAvg automata not determinizable:

Σ^*b^ω expressible by nondeterministic LimAvg automaton.



Σ^*b^ω not expressible by deterministic limAvg automaton.

Every b-cycle would need weight 1.

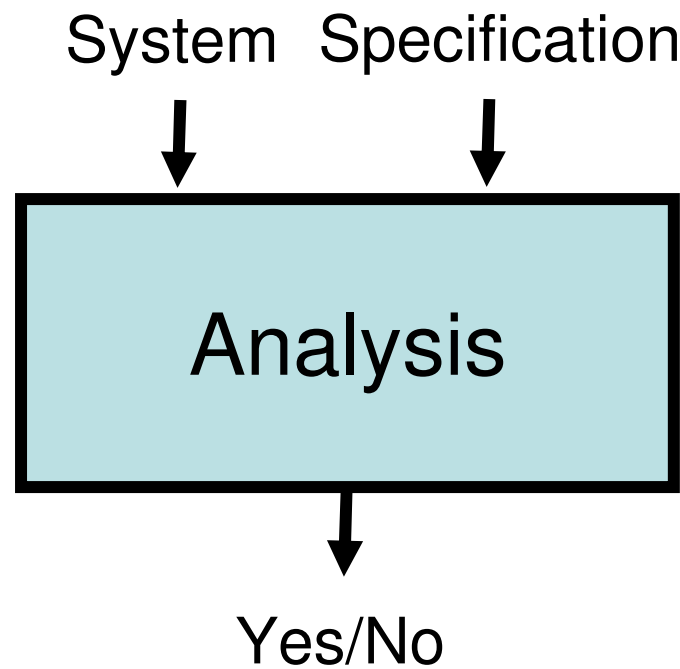
Consider $w_n = (ab^n)^\omega$.

Then $\text{val}(w_n)=1$ for sufficiently large n , but $w_n \notin \Sigma^*b^\omega$.

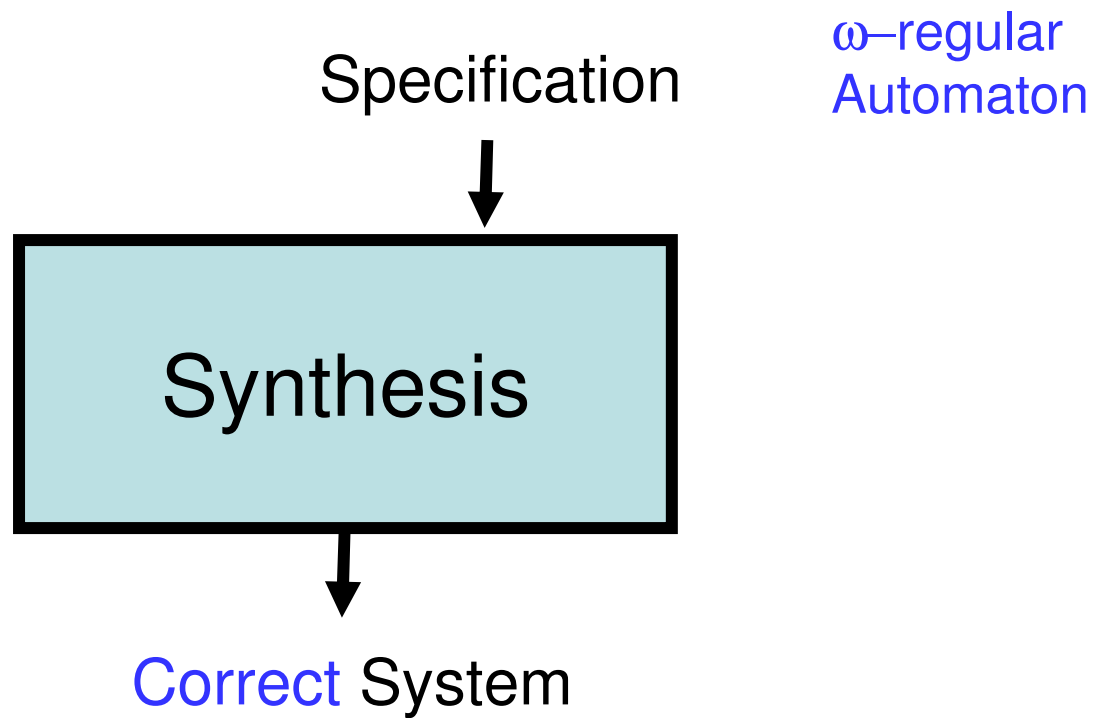
Outline

- 1 The Quantitative Agenda
- 2 Some Basic Open Problems
- 3 Some Promising Directions

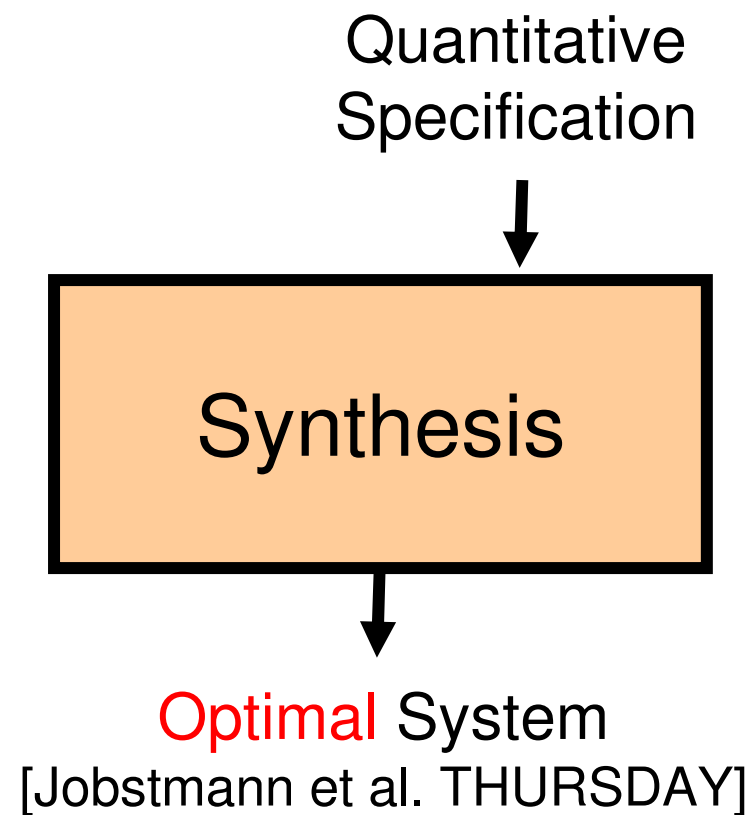
The Boolean Agenda



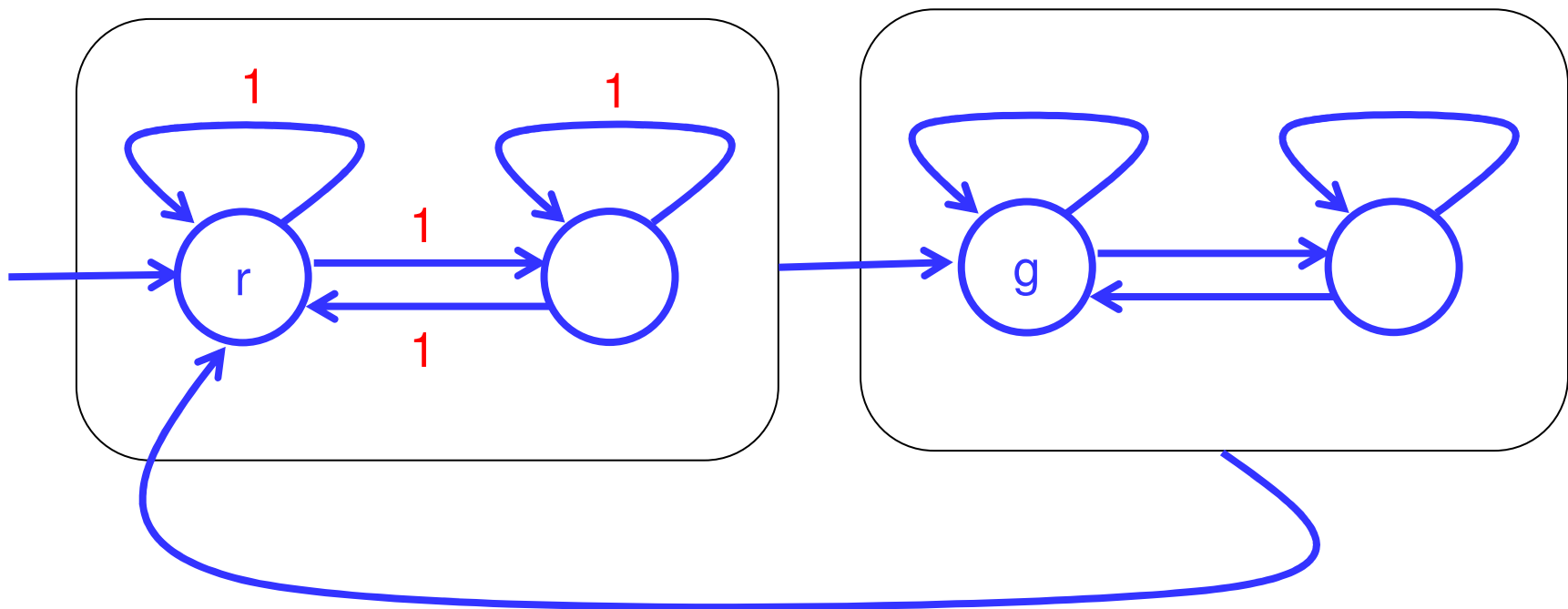
The Boolean Agenda



3.1 Quantitative Synthesis

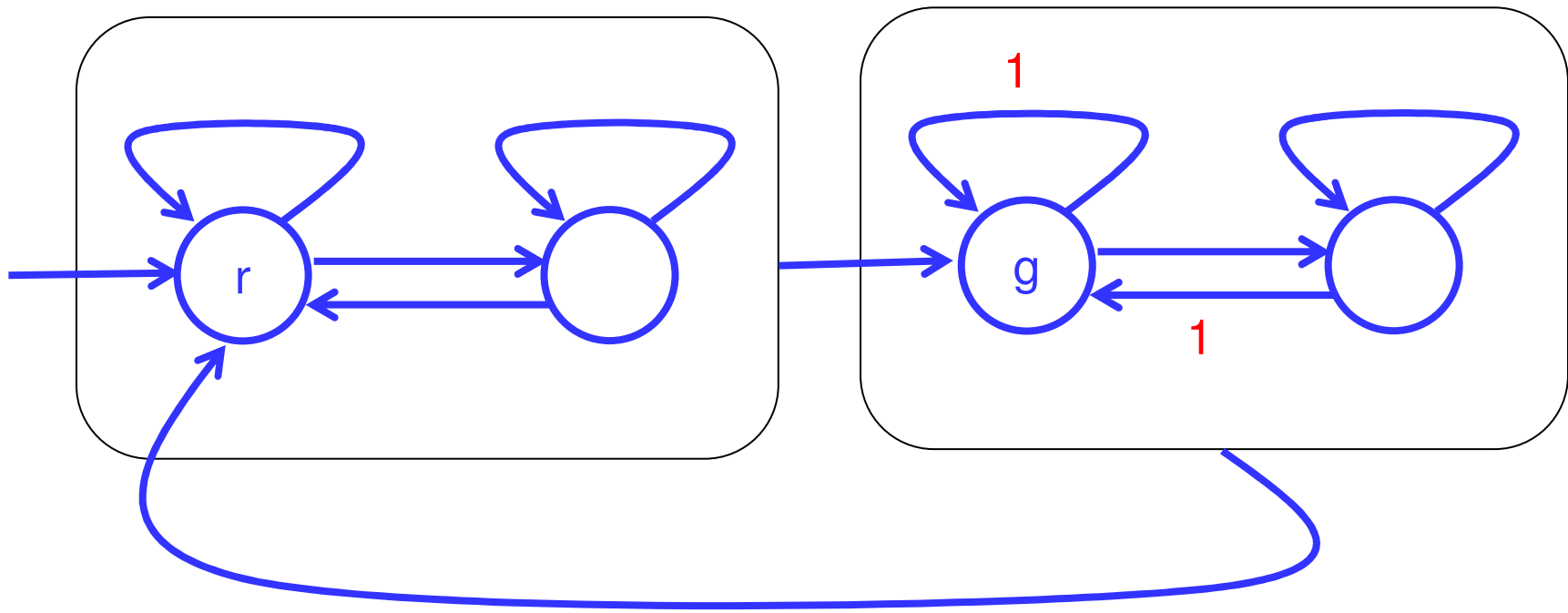


Request-Grant Automaton 1



Following a request, all steps until the next grant are penalized.

Request-Grant Automaton 2



Following a request, all repeated grants are penalized.

3.2 Robust Systems

A Robustness as Mathematical Continuity:

- small input changes cause small output changes
- only possible in a quantitative framework

$$\forall \varepsilon > 0. \exists \delta > 0. \text{input-change} \leq \delta \Rightarrow \text{output-change} \leq \varepsilon$$

In general programs are not continuous.
But they can be more continuous:

```
read sensor value x at time t;  
compute “continuous” function  $y = f(x)$ ;  
write output value y at time  $t + \delta$ .
```

Or less continuous:

```
read sensor value x;  
if  $x \leq c$  then  $y = f_1(x)$   
else  $y = f_2(x)$ ;
```

In general programs are not continuous.
But they can be more continuous:

```
read sensor value x at time t;  
compute continuous function  $y = f(x)$ ;  
write output value y at time t+d;
```

Or less continuous:

```
read sensor value x;  
if  $x \leq c$  then  $y = f_1(x)$   
  else  $y = f_2(x)$ ;
```

Better:

```
if  $x \leq c - \epsilon$  then  $y = f_1(x)$ ;  
if  $x \geq c + \epsilon$  then  $y = f_2(x)$   
  else  $y =$ 
```

$$(f_2(c+\epsilon)-f_1(c-\epsilon))(x-c+\epsilon)/2\epsilon + f_1(c-\epsilon)$$

[Majumdar et al., Gulwani et al.]

3.2 Robust Systems

A Robustness as Mathematical Continuity:

- small input changes cause small output changes
- only possible in a quantitative framework

$$\forall \varepsilon > 0. \exists \delta > 0. \text{input-change} \leq \delta \Rightarrow \text{output-change} \leq \varepsilon$$

Example of a Robustness Theorem [AHM]:

If $\text{discountedBisimilarity}(A, B) > 1 - \varepsilon$,
then $\forall w : |A(w) - B(w)| < f(\varepsilon)$.

3.2 Robust Systems

A Robustness as Mathematical Continuity:

- small input changes cause small output changes
- only possible in a quantitative framework

B Robustness w.r.t. Faulty Assumptions:

- few environment mistakes cause few system mistakes
- ratio of system to environment mistakes as quantitative quality measure

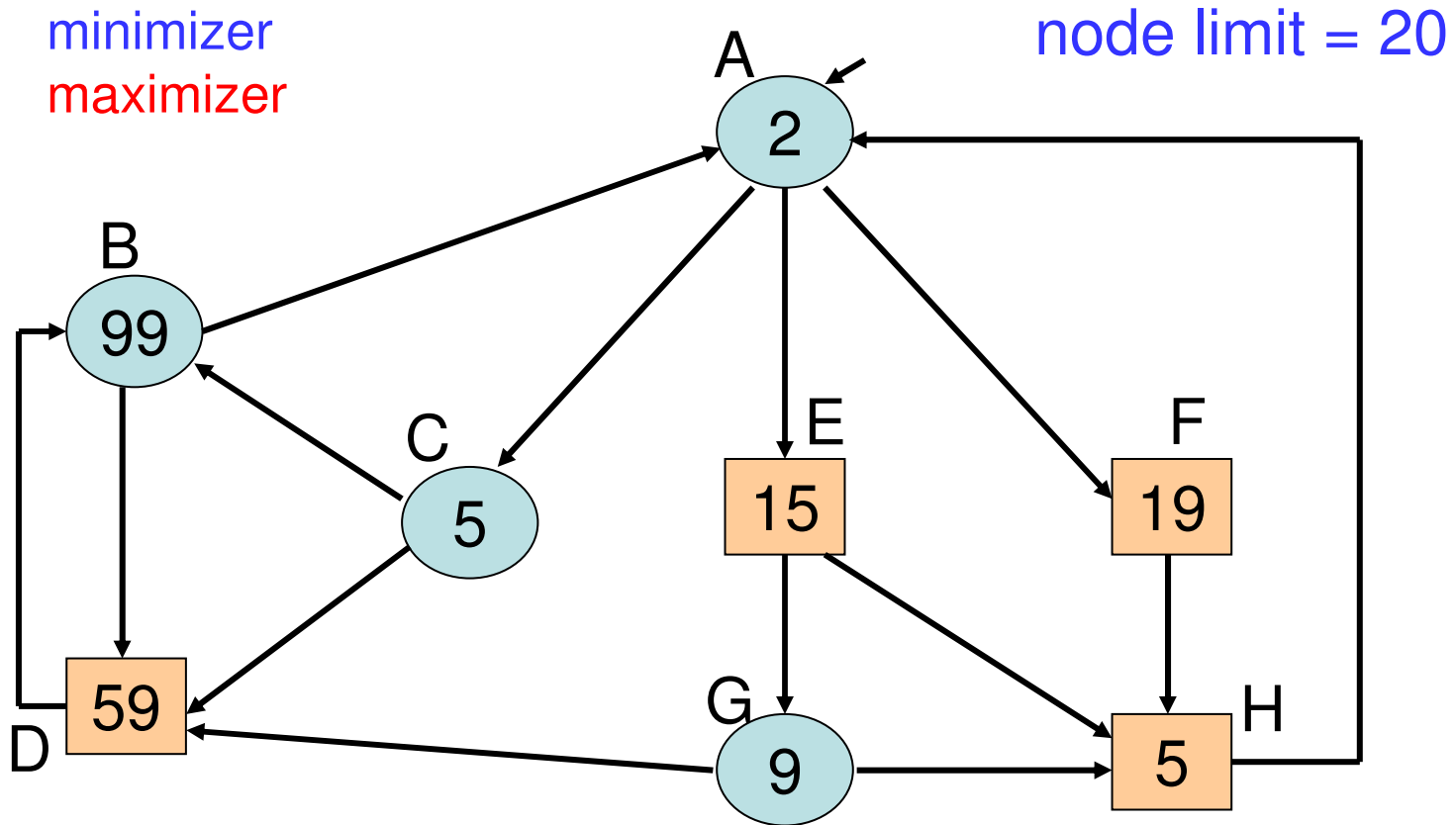
[Greimel et al. TODAY]

3.3 Resource Interfaces

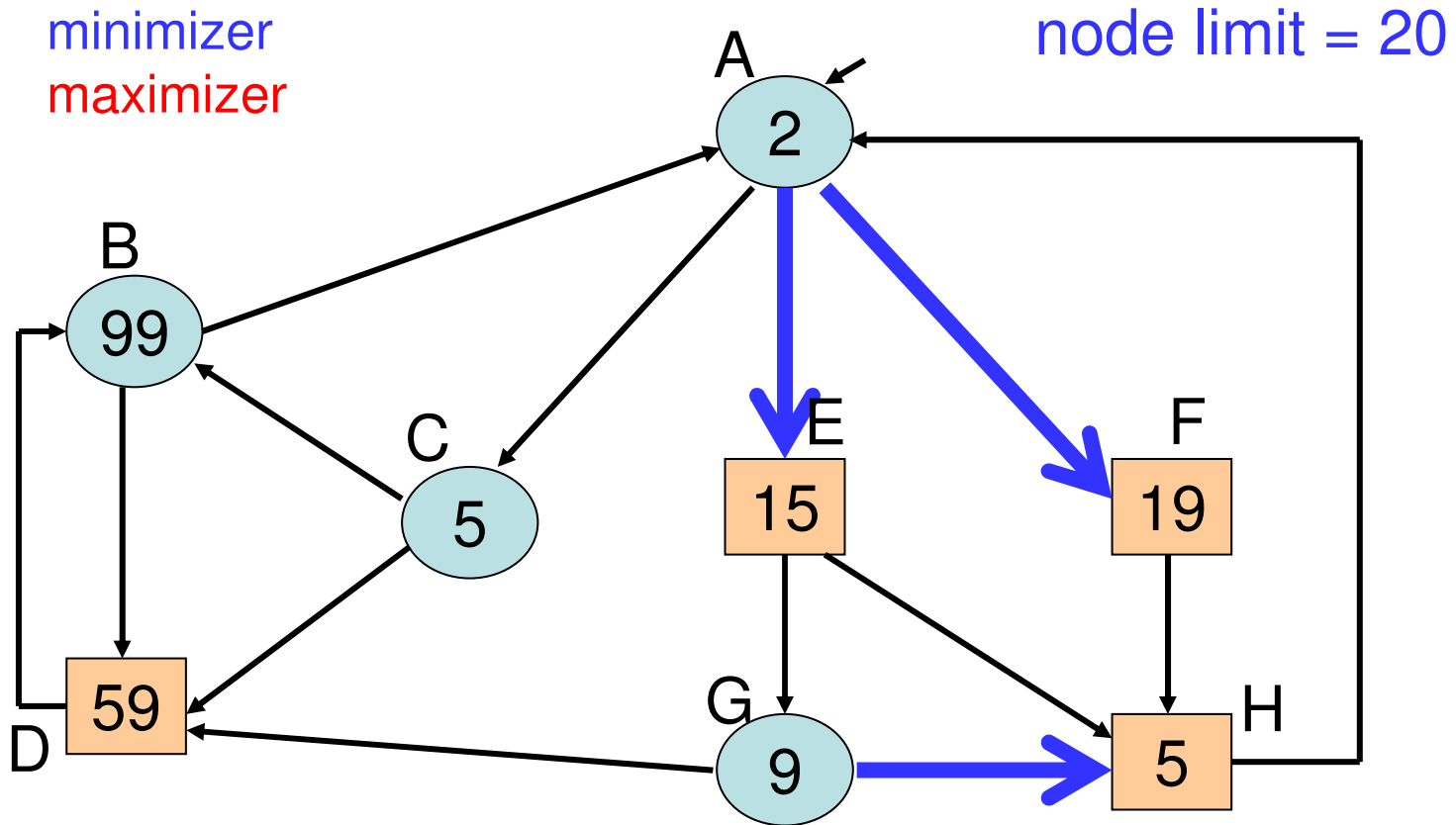
- Component interfaces expose resource requirements (e.g. time, memory, power).
- Interfaces are compatible if their combined requirements do not exceed the available resources.
- If the requirements are dynamic, then compatibility can be solved as a graph game with quantitative objectives.

[Chakrabarti et al.]

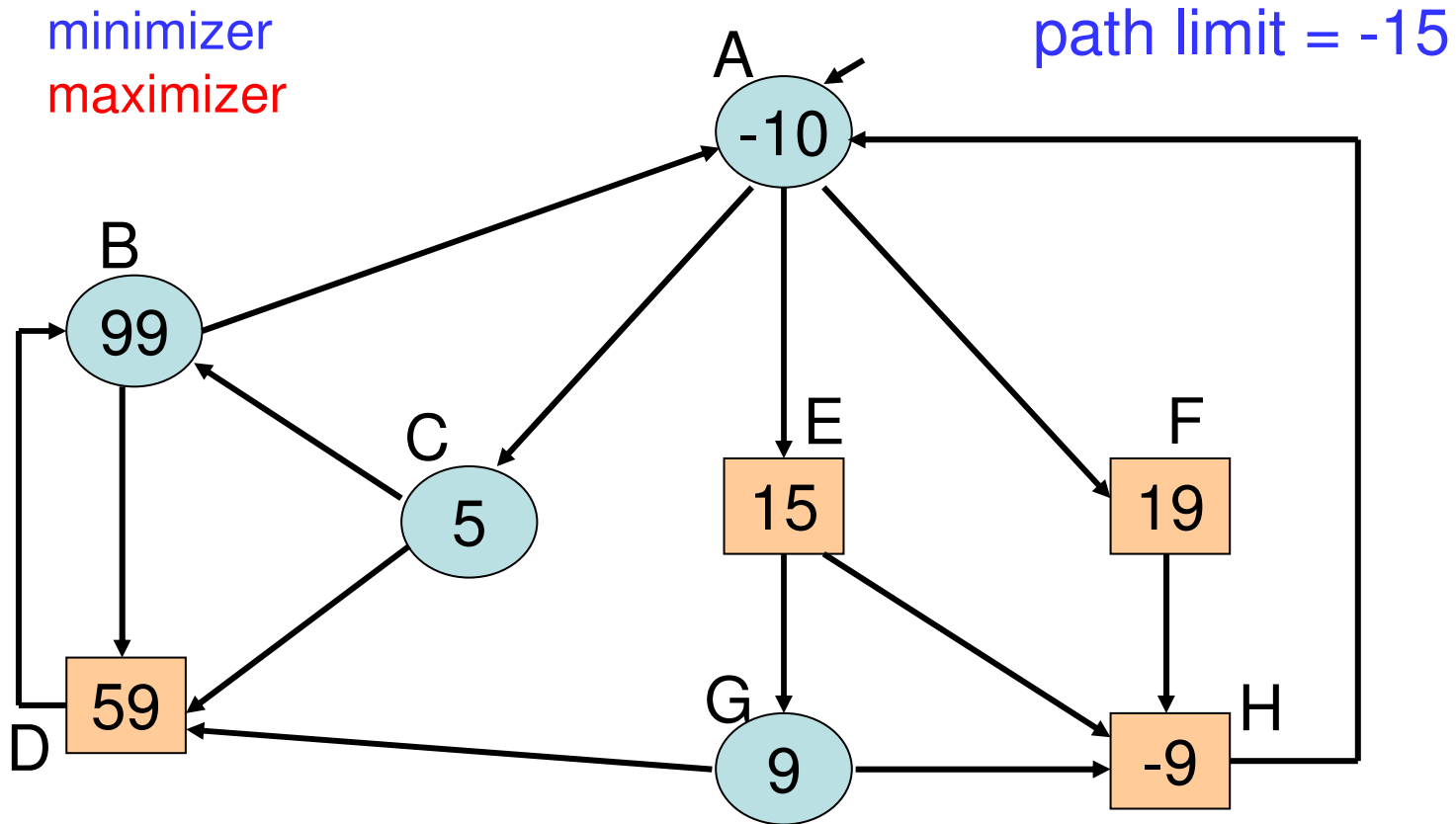
Max Value Constraint



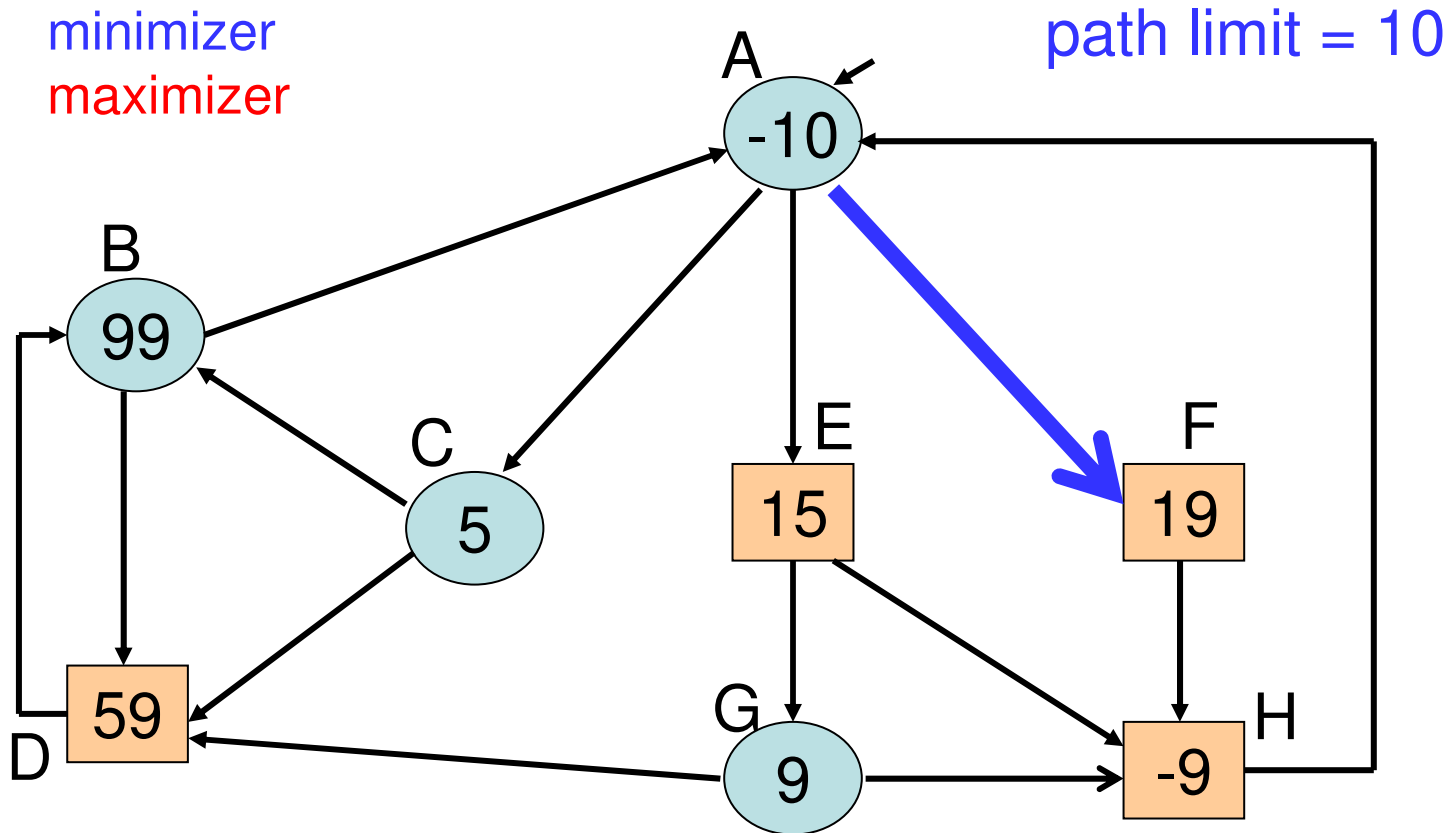
Max Value Constraint



Sum Constraint



Sum Constraint



3.4 System Reliability

- assuming $x\%$ of input values are valid,
 $y\%$ of output values should be valid (limavg)
 - hardware faulty, but can be replicated
 - compiler ensures specified reliability through replication
- [Ghosal et al.]

3.4 System Reliability

a: ok

b: fail

Limit-average value:

aaaaaaaaaa...	1
aaabaaabaaab...	3/4
abaabaaab...	0

Want reliability of $1 - 10^{-x}$.

Conclusions

- “Quantitative” is more than “timed” and “probabilistic.”
- We need to move from boolean correctness criteria to quantitative system preference metrics.
- We have interesting point solutions, but no convincing overall framework.