

An information-theoretic view of the Witsenhausen Counterexample

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presenting joint work with students:

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2009 ITA in UCSD, La Jolla

Ho, Kastner, Wong '78

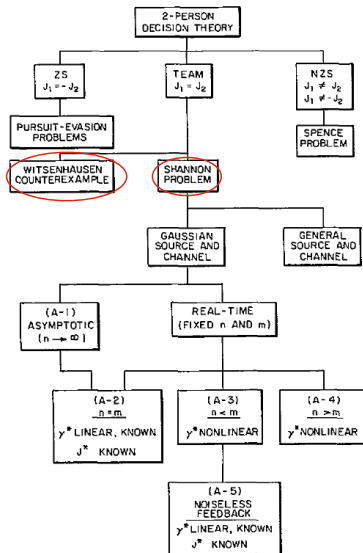
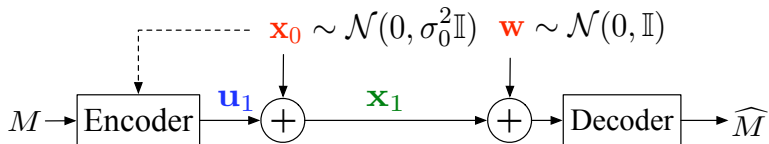
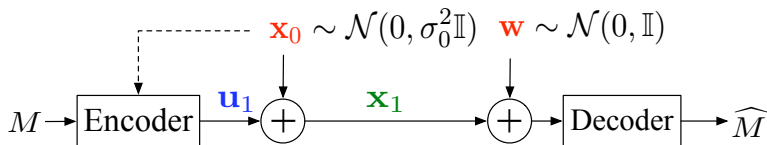


Fig. 1. Teams, signaling, and information theory.

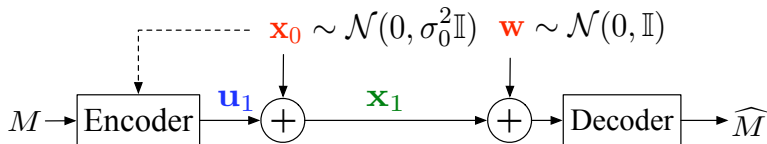


Dirty paper coding



Dirty paper coding

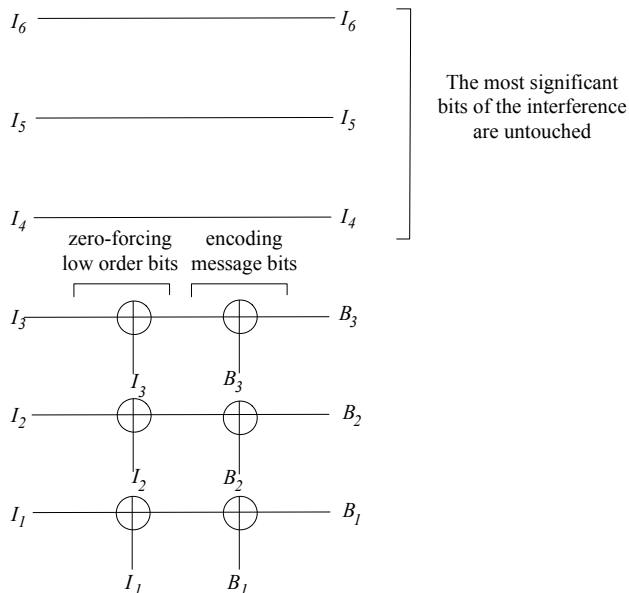
- **State Amplification:** also estimate \mathbf{x}_0 (inspired by Devroye, *et al* '06 and following up on Sutivong, *et al* '05)

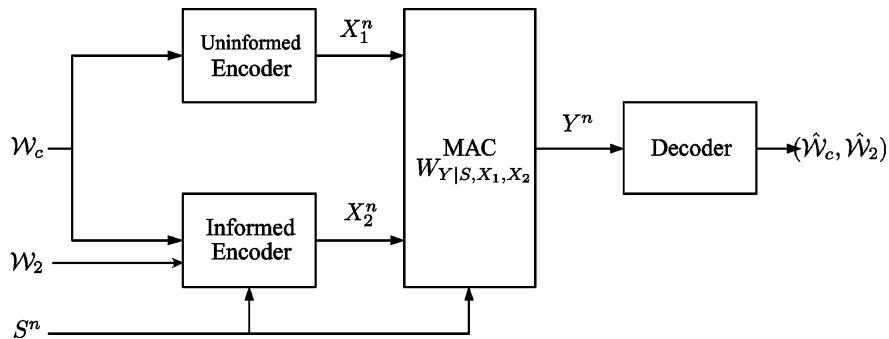


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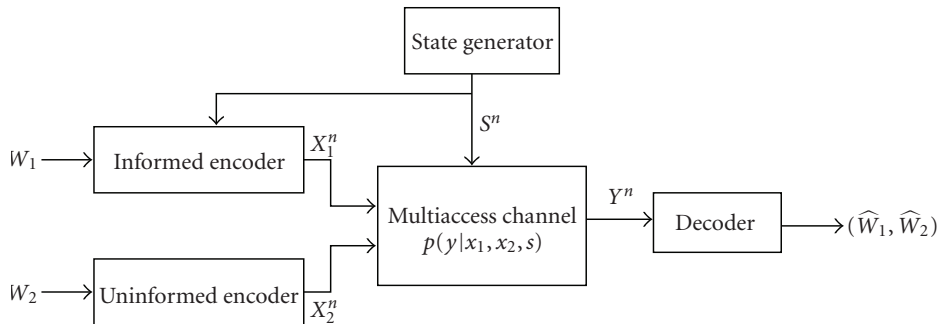
- State Amplification: also estimate \mathbf{x}_0 (inspired by Devroye, *et al* '06 and following up on Sutivong, *et al* '05)
- State Masking: obscure \mathbf{x}_0

Deterministic perspective: can DPC be distributed?

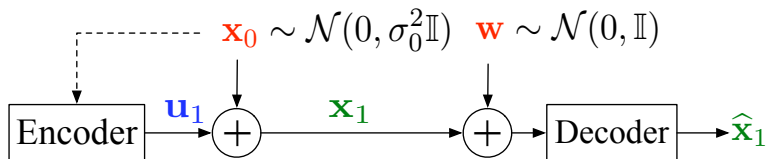




Kotagiri and Laneman '08



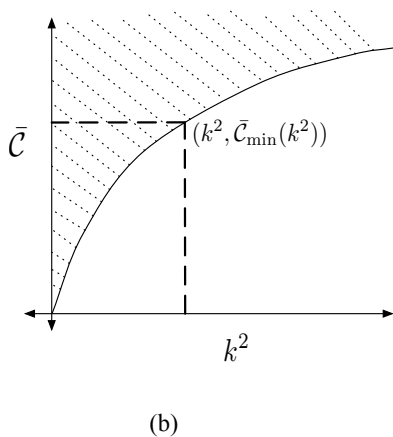
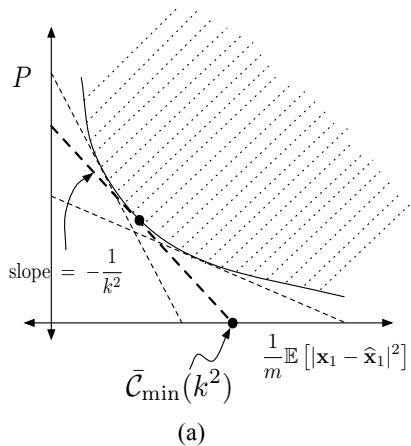
Simplify: eliminate both messages!



$$\mathbb{E}[C] = k^2 P + \frac{1}{m} \mathbb{E} [\|\mathbf{x}_1 - \hat{\mathbf{x}}_1\|^2]$$

The vector Witsenhausen counterexample

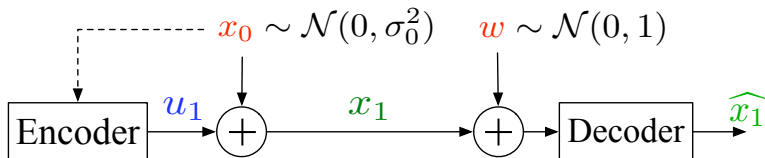
Two equivalent perspectives



Outline

- Towards the “simplest” unsolved problem
- **The perspective from control theory**
- A new bound and an approximately optimal solution
- Approximate optimality in the scalar case

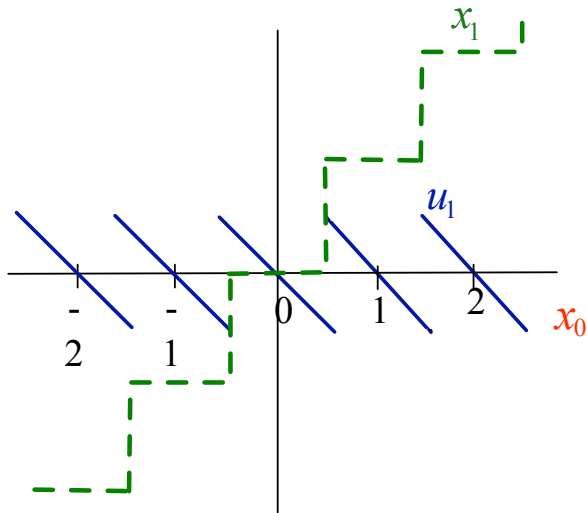
Witsenhausen '68

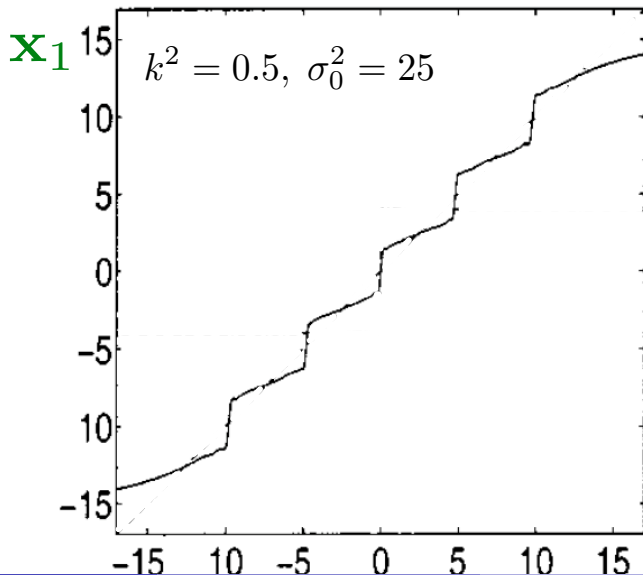


The scalar Witsenhausen counterexample

$$\mathcal{C} = k^2 u_1^2 + (x_1 - \hat{x}_1)^2$$

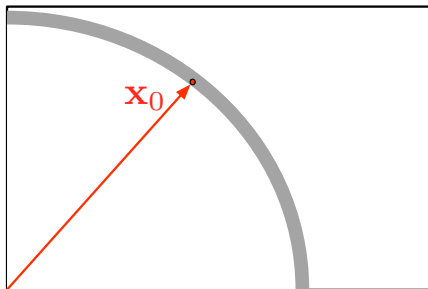
Mitter and Sahai '99



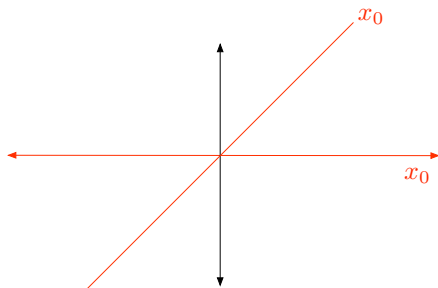


The connection with DPC

Vector

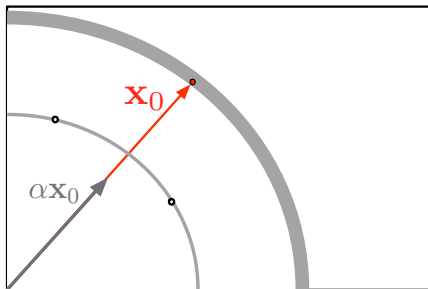


Scalar

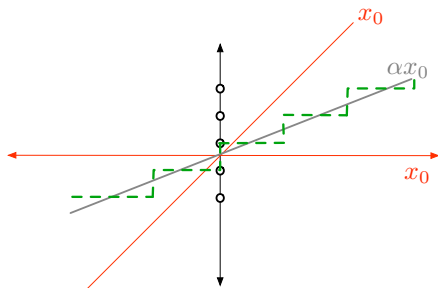


The connection with DPC

Vector

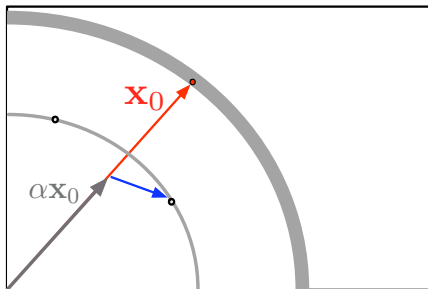


Scalar

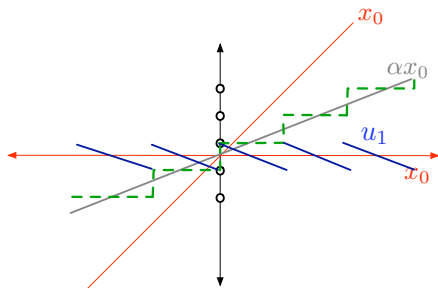


The connection with DPC

Vector

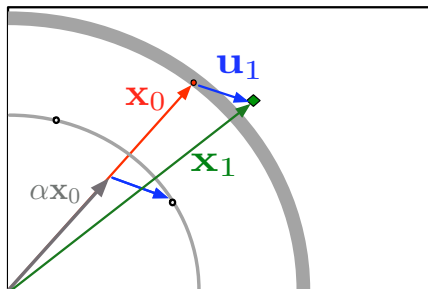


Scalar

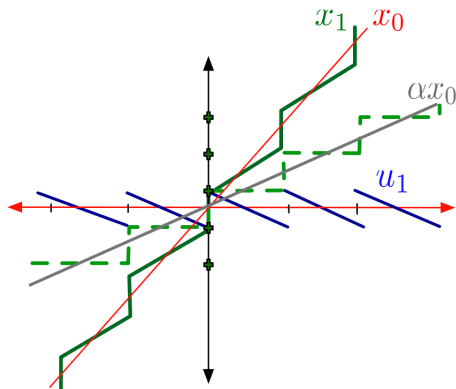


The connection with DPC

Vector

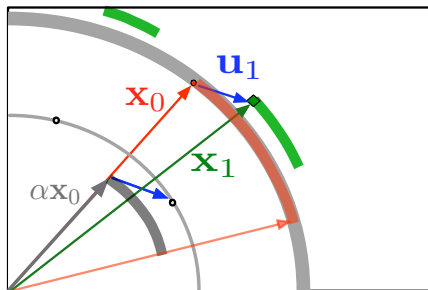


Scalar

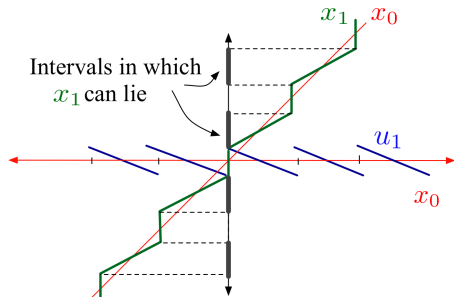


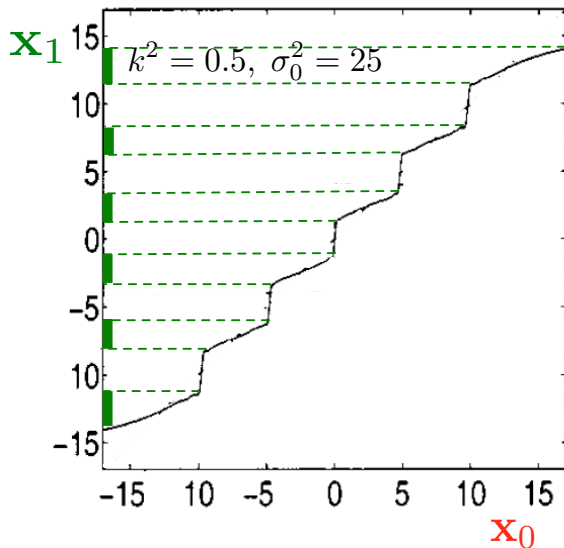
The connection with DPC

Vector



Scalar

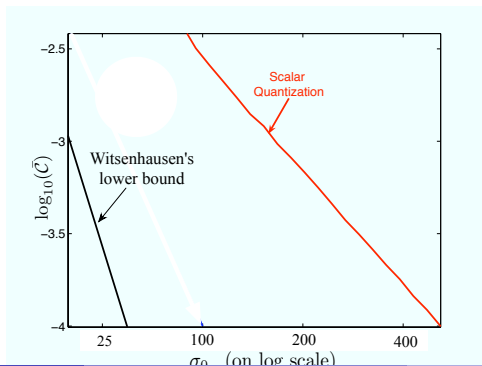




Witsenhausen's scalar lower bound

$$\bar{C}_{\min}^{\text{scalar}} \geq \frac{1}{\sigma_0} \int_{-\infty}^{+\infty} \phi\left(\frac{\xi}{\sigma_0}\right) V_k(\xi) d\xi,$$

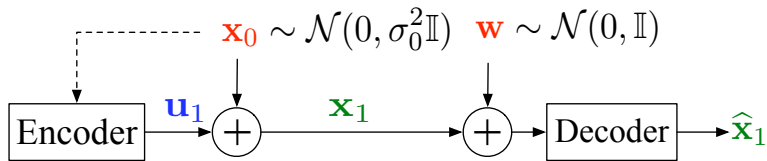
where $\phi(t) = \frac{1}{\sqrt{2\pi}} \exp(-\frac{t^2}{2})$, $V_k(\xi) := \min_a [k^2(a - \xi)^2 + h(a)]$, and $h(a) := \sqrt{2\pi} a^2 \phi(a) \int_{-\infty}^{+\infty} \frac{\phi(y)}{\cosh(ay)} dy$.



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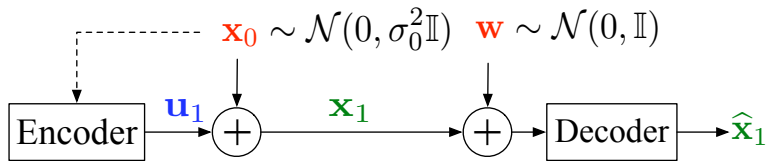
The core tension



$$\mathbb{E}[\mathcal{C}] = k^2 P + \frac{1}{m} \mathbb{E} [\|\mathbf{x}_1 - \hat{\mathbf{x}}_1\|^2]$$

The vector Witsenhausen counterexample

The new bound



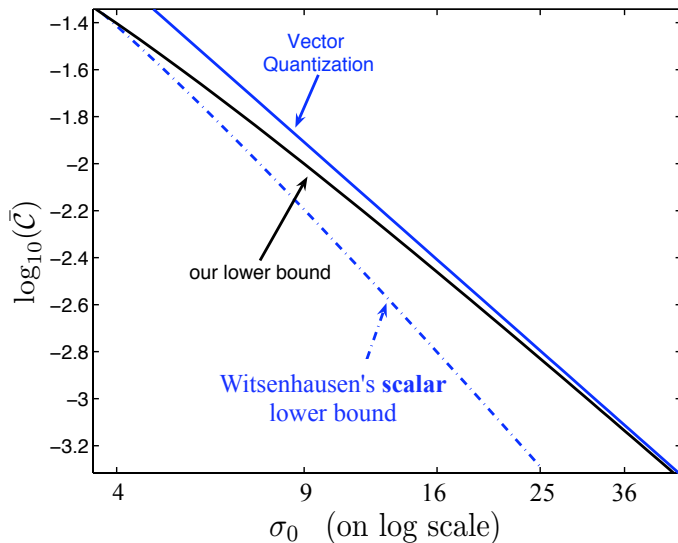
$$\mathbb{E}[\mathcal{C}] = k^2 P + \frac{1}{m} \mathbb{E} [\|\mathbf{x}_1 - \hat{\mathbf{x}}_1\|^2]$$

The vector Witsenhausen counterexample

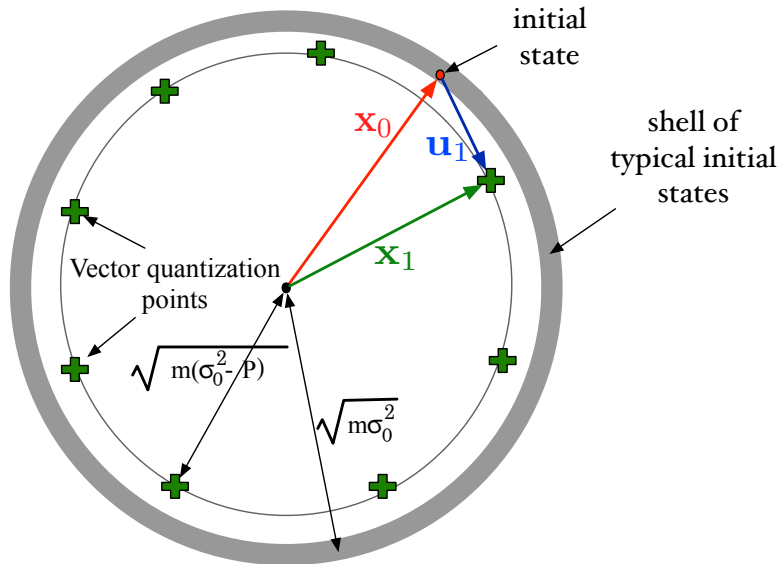
$$\bar{\mathcal{C}}_{\min} \geq \inf_{P \geq 0} k^2 P + \left((\sqrt{\kappa(P)} - \sqrt{P})^+ \right)^2,$$

$$\text{where } \kappa(P) = \frac{\sigma_0^2}{\sigma_0^2 + 2\sigma_0\sqrt{P} + P + 1}.$$

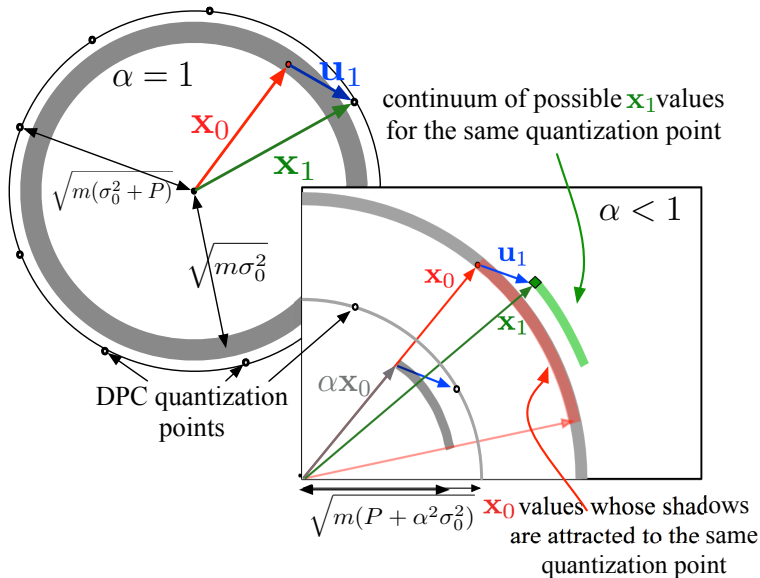
Comparison with old bound



Achievability

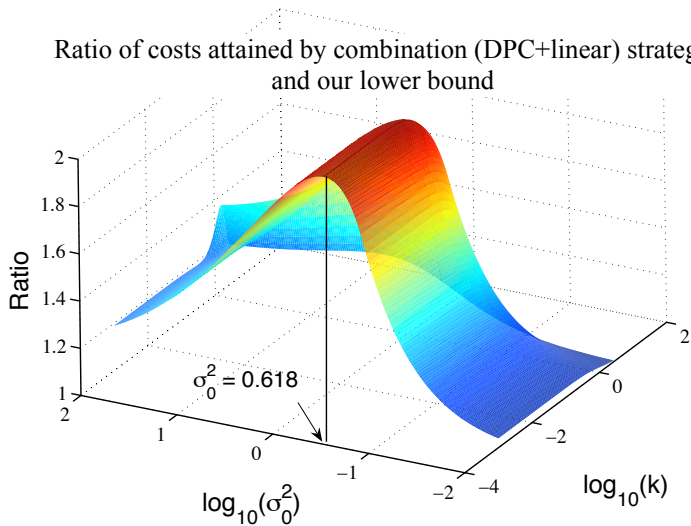


Achievability

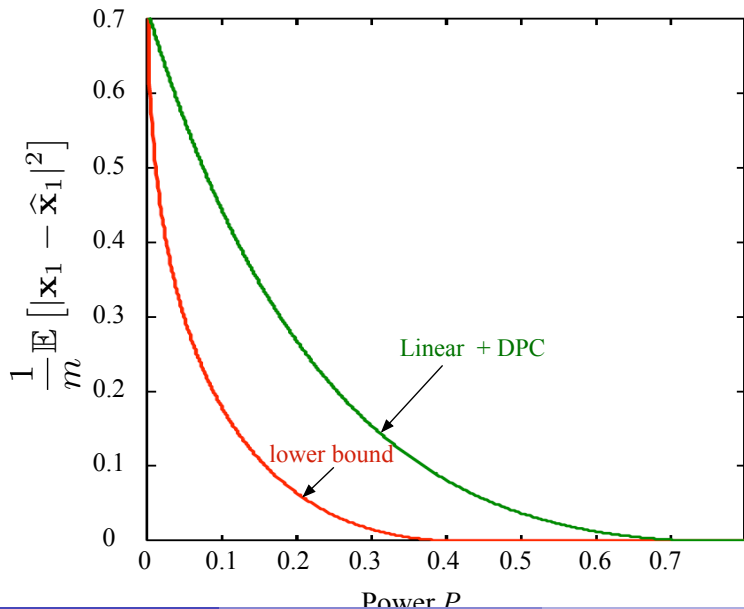


Constant factor bound

Ratio of costs attained by combination (DPC+linear) strategy
and our lower bound



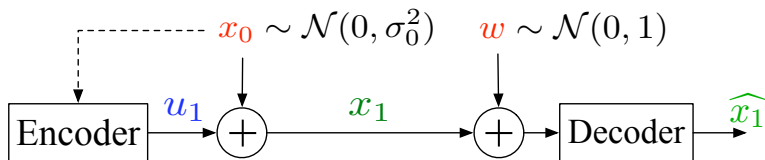
Constant factor bound



Outline

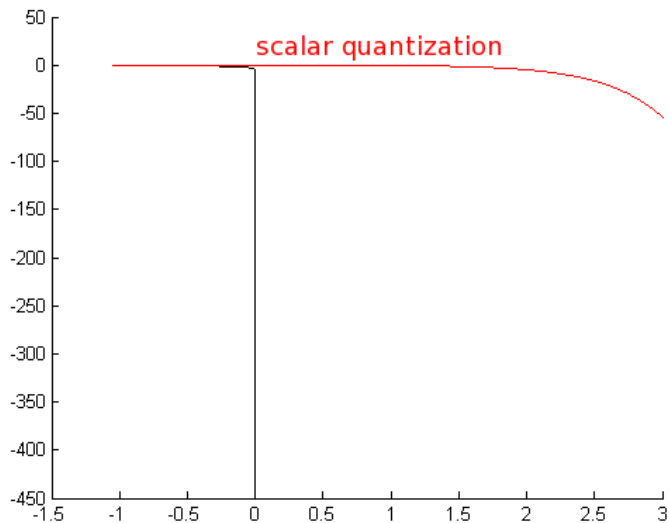
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Back to the control setting

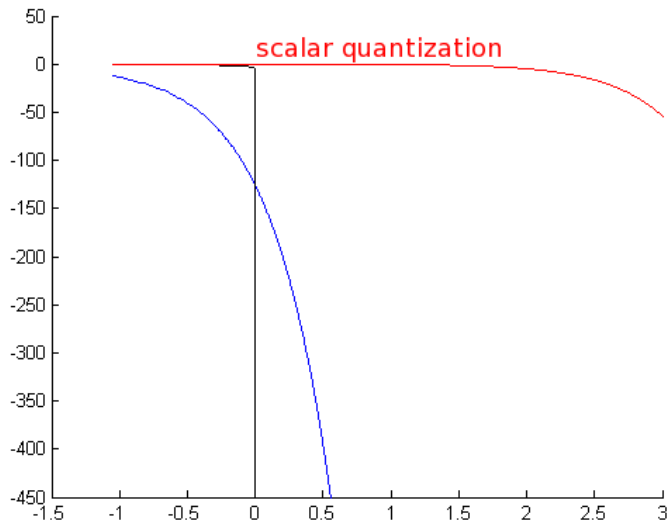


The scalar Witsenhausen counterexample

Back to the control setting



Back to the control setting



Conclusions

- The Witsenhausen counterexample is the “simplest” unsolved problem in information theory.
- Standard tools give a constant-factor result in asymptopia
- We need non-asymptotic approximation guarantees too