

# New results on source and channel coding error exponents with respect to end-to-end delay

*The power of “punctuation”*

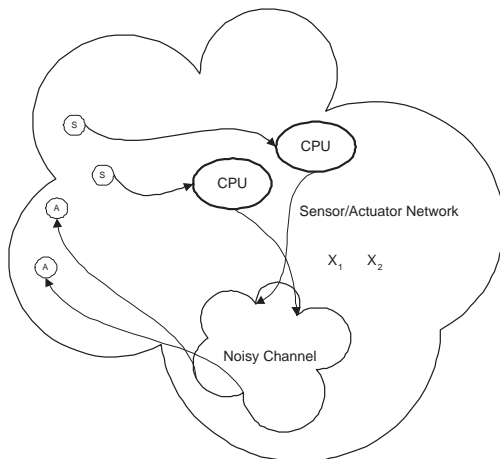
Cheng Chang and Anant Sahai

Wireless Foundations  
Department of Electrical Engineering and Computer Science  
University of California, Berkeley

Asilomar 2006

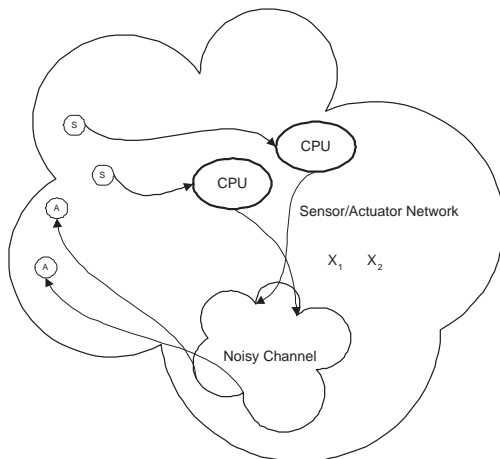
# Motivation

- Many applications are embedded in time



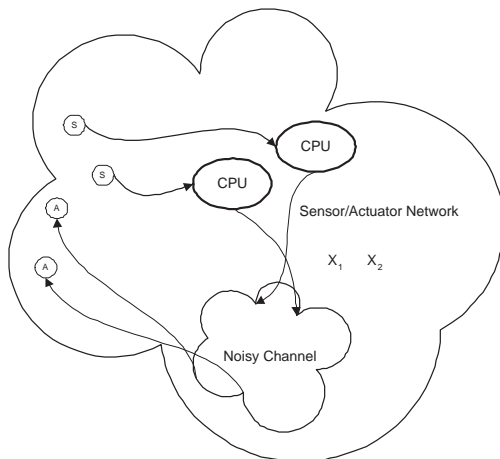
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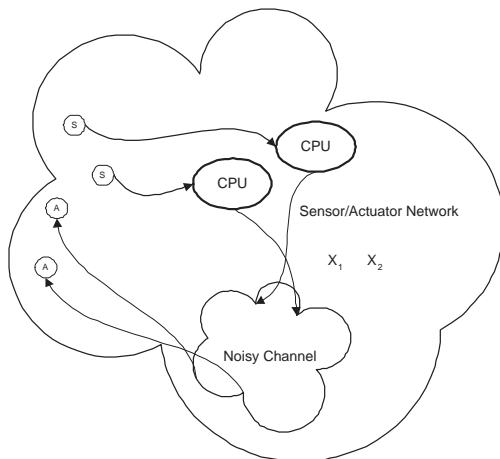
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- Many applications are embedded in time
  - ▶ Want low end-to-end delay
  - ▶ Want “cheap” channels
  - ▶ Want “modular” implementations



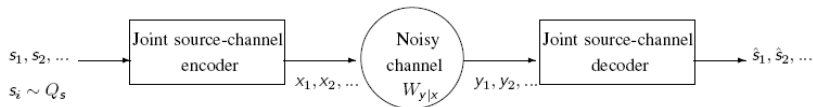
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- Lossless source-channel coding (synchronized)
  - ▶ One source symbol per channel use



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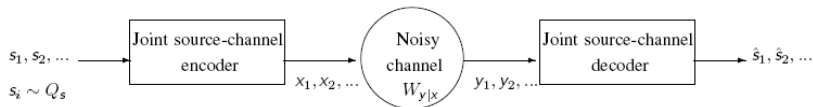
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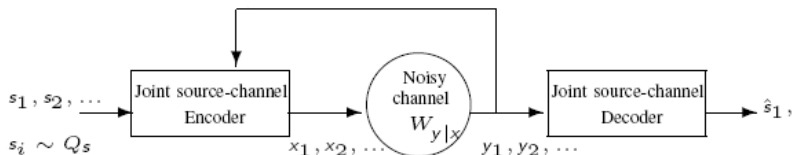
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  - ▶ What quality channel is required to get performance?
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  - ▶ Is feedback worth using?

# Outline

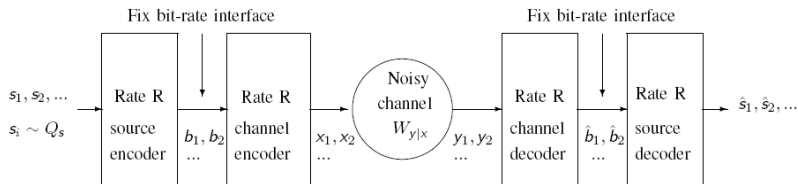
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# Review: block coding perspective on channel quality

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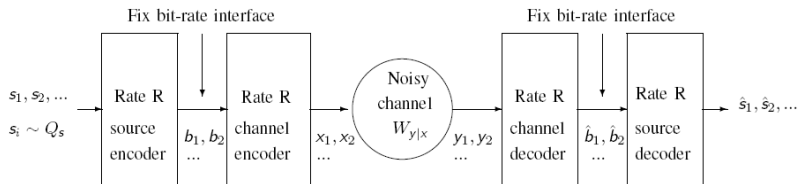
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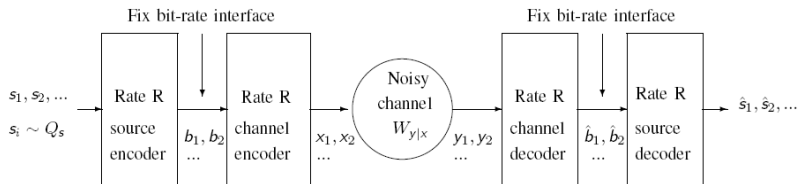
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  - ▶ If delay is not important, use long block-codes.
  - ▶ Feedback is irrelevant if channel is memoryless.

## Review: How long of a block?

- Decoding error  $\Pr(s_1^n \neq \hat{s}_1^n)$  vs code-length :
  - ▶ Error exponent given  $S, W$ :

$$E^b := \lim_{n \rightarrow \infty} -\frac{1}{n} \log \Pr(s_1^n \neq \hat{s}_1^n)$$

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- ▶ Lossless source coding (Csiszár and Körner):  $R \geq H(S)$

$$e^b(R) = \min_{P_s: H(P_s) \geq R} D(P_s \| Q_s)$$

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- ▶ Separate source channel coding

$$\Pr(s \neq \hat{s}) \leq \Pr(b \neq \hat{b}) + \Pr(s \neq \hat{s}(b) | b = \hat{b}):$$

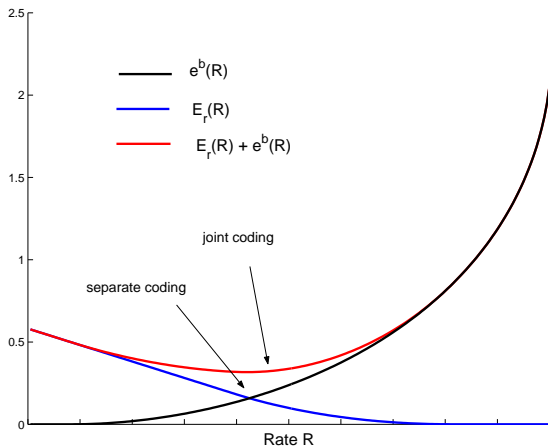
$$E^b \geq \max_R \min \{e^b(R), E^b(R)\}$$

# The delay price of modularity?

- Joint strictly better than separate (Csiszár):

- ▶ Error exponent (tight if  $R^* \geq R_{cr}$ ):

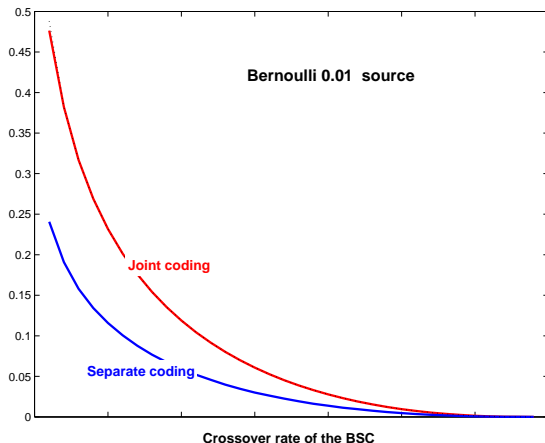
$$E^b \in \left[ \min_{H(S) \leq R \leq C(W)} \{e^b(R) + E_r(R)\}, \min_{H(S) \leq R \leq C(W)} \{e^b(R) + E_{sp}(R)\} \right]$$



# Pay with delay or with channels

- Random coding error exponents (Bernoulli 0.01 source over BSC)

- ▶ **Joint coding:**  $\min_{H(S) \leq R \leq C(W)} \{e^b(R) + E_r(R)\}$
- ▶ **Separate coding:**  $\max_R \min\{e^b(R), E_r(R)\}$

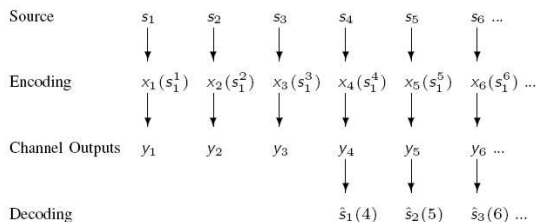


# But is block-coding the problem?

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- The real problem with delay constraints:
  - ▶ Source symbols  $s_1, s_2, \dots, s_k, \dots$  streaming into the encoder
    - Causality: source symbol  $s_i$  not available at time  $i - 1$
  - ▶ Finite and fixed system delay



- ▶ Want symbol-wise decoding error tradeoff with delay:

$$\Pr(s_i \neq \hat{s}_i(i + \Delta)) \sim 2^{-\Delta E^s}$$

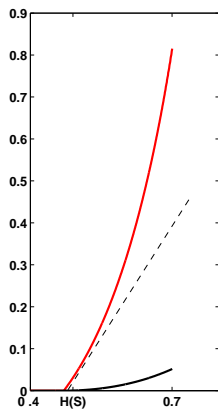
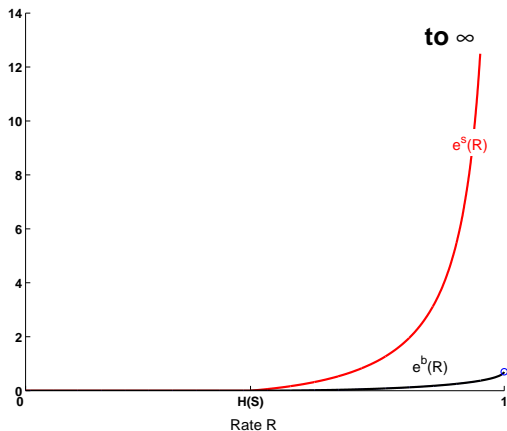
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# A cause for hope: fixed rate source coding (ITW06)

- Tight bound achieved by variable length coding/queueing:

$$e^s(R) = \min_{P_s, \alpha > 0: H(P_s) > (1+\alpha)R} \left\{ \frac{1}{\alpha} D(P_s \| Q_s) \right\} = \min_{\alpha > 0} \frac{1}{\alpha} e^b((1+\alpha)R)$$

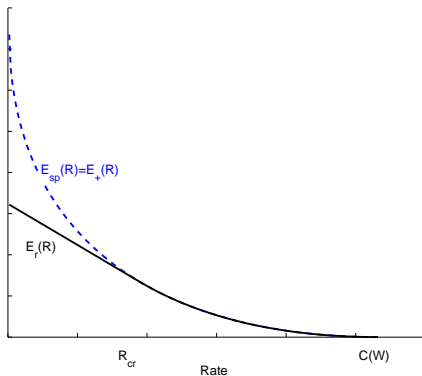


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- Random coding error exponent  $E_r(R)$  achievable
- Upper bounded by Haroutunian bound  $E_+(R)$  (Pinsker, Sahai)
  - ▶  $E_+(R) = E_{sp}(R)$  for symmetric channels (BEC, BSC...)
  - ▶ Proved by feedforward decoding



# A joint-coding bound (Allerton 2006)

- Delay constrained lossless source-channel coding error exponent

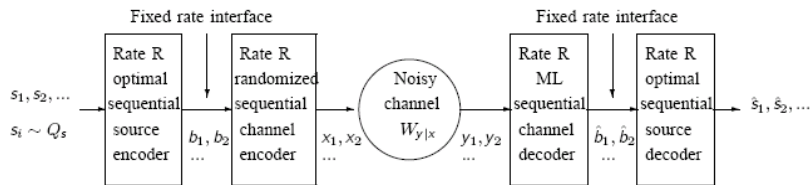
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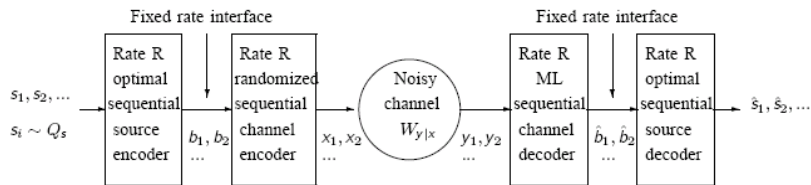
- Block coding counterpart (Csiszár):

$$E^b \leq \min_R \{e^b(R) + E_{sp}(R)\}$$

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- Union bound on  $\Pr(s_i \neq \hat{s}_i(i + \Delta))$



$$\begin{aligned}
 & \sum_{k=1}^i \Pr(b_k \neq \hat{b}_k) + \sum_{k=i+1}^{i+\Delta} \Pr(b_k \neq \hat{b}_k, b_1^{k-1} = \hat{b}_1^{k-1}) \Pr(s_i \neq \hat{s}_i(b_1^{k-1})) \\
 & \approx 2^{-\Delta} \max_R \min\{e^s(R), E_r(R)\}
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- Drain the source-queue at rate  $R'$ .
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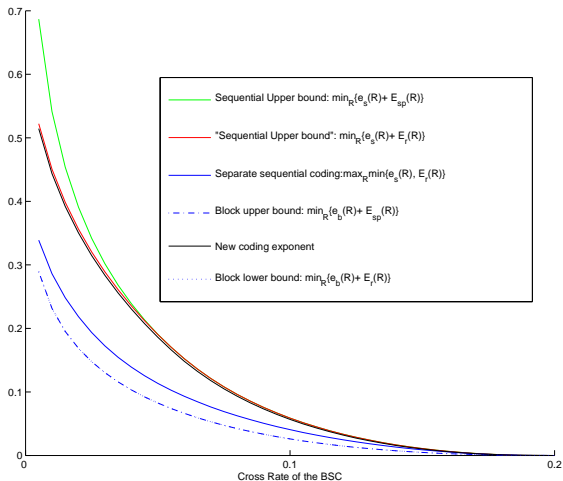
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- Error exponent

$$\max_{R'} \min_{\alpha > 0, R \in [0, R']} \left\{ \alpha e^s(R') + e^b((1 - \alpha)R) + (1 - \alpha)E_r(R) \right\}$$

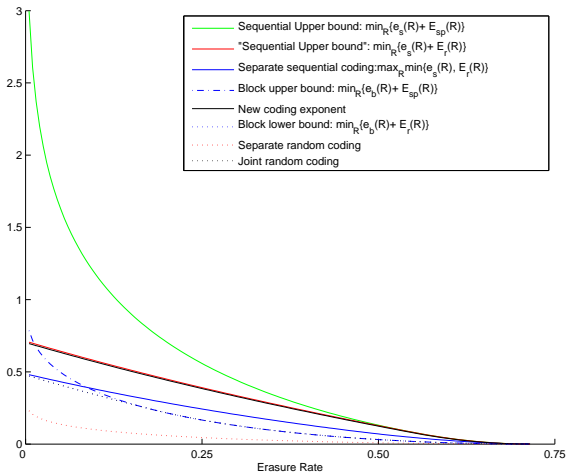
# Examples (no feedback)

- Delay exponents of a Bernoulli  $\frac{1}{20}$  source and BSCs



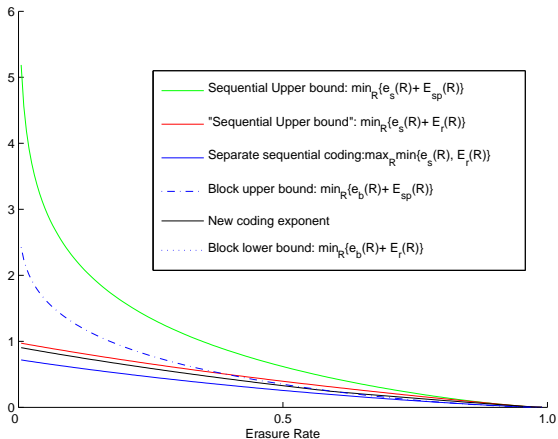
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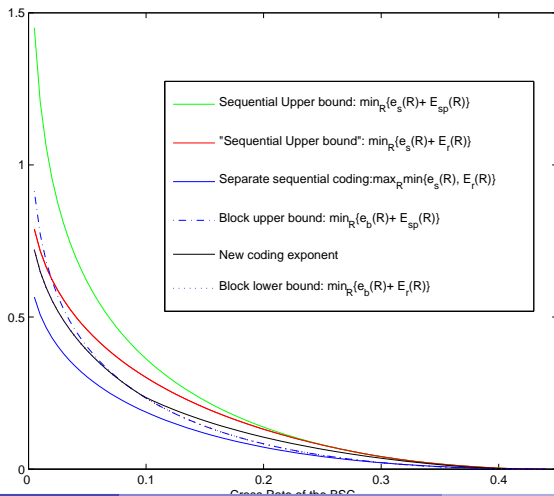
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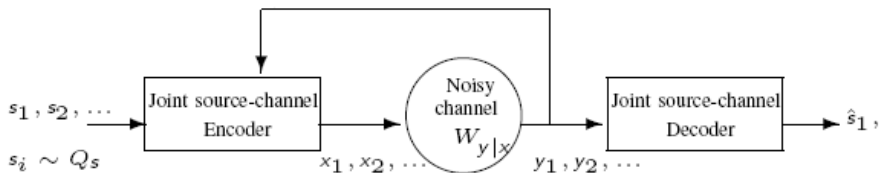
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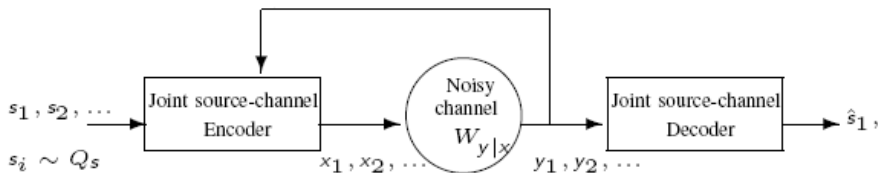
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## Add channel feedback



- Capacity unchanged:  $H(S) < C(W)$

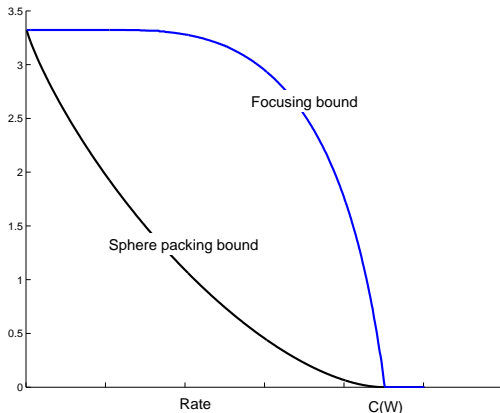
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- Capacity unchanged:  $H(S) < C(W)$
- What about error exponents?
  - ▶ Block coding: upper bound still holds ( $\min_R \{e^b(R) + E_+(R)\}$ )
  - ▶ For symmetric channels, upper bound tight if  $R^* \geq R_{cr}$
  - ▶ No gain with feedback!

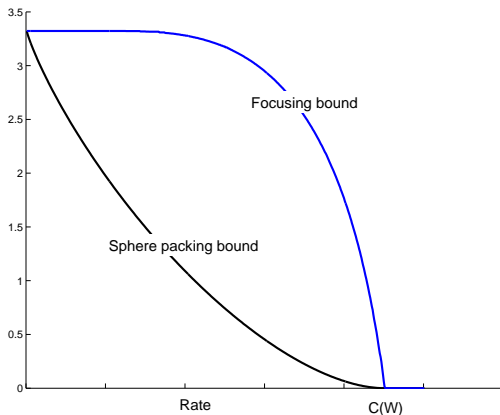
# More hope: channel coding with feedback (Sahai06)

- Uncertainty focusing bound  $\min_{0 < \lambda < 1} \frac{E_+(\lambda R)}{1 - \lambda}$  (Sahai)
  - ▶ With “free punctuation,” can achieve using variable length codes and queuing



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- Can we do better for joint source channel coding with feedback, too?

# The upper bound (Allerton 2006)

- Delay constrained lossless source-channel coding error exponent with feedback

$$E_f^s \leq \min_{\lambda \in [0,1], R} \left\{ \frac{\lambda}{1-\lambda} e(R) + \frac{1}{1-\lambda} E_+(\lambda R) \right\}$$

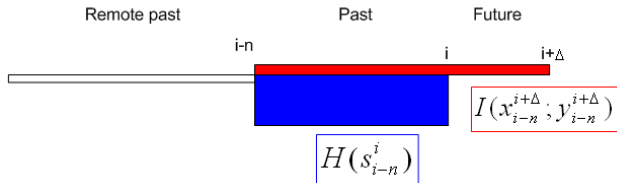
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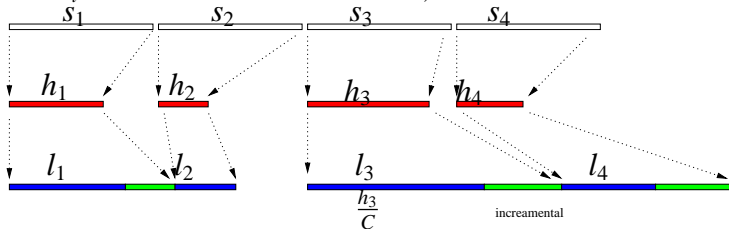
- Proof sketch

- ▶ An symbol error occurs if  $H(s_{i-n}^i) > I(x_{i-n}^{i+\Delta}; y_{i-n}^{i+\Delta})$
- ▶ For a fixed  $\Delta$ , minimizing over  $n$  (dominant error event),  $\lambda = \frac{n}{n+\Delta}$



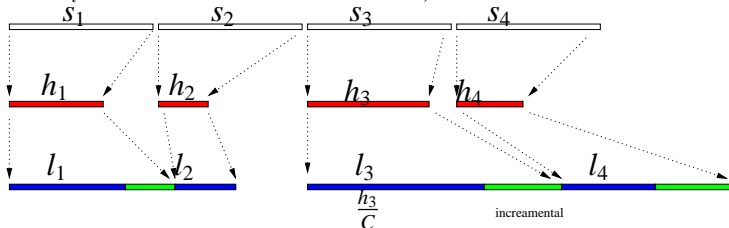
# Achieving the bound using free punctuation

- Coding scheme (variable length to variable length)
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- “Punctuation” is very low rate:
  - ▶ Source-block sizes:  $\frac{\log n}{n}$
  - ▶ Stopping time

# How to analyze error probability

- $t_i = \sum_{k=1}^i l_k$ : time the decoder can decode source symbol  $i$
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  - ▶ Error event: symbol still in queue.
  - ▶ Decoding error for  $s_i$  at time  $i + \Delta$  iff  $t_i > i + \Delta$
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- Apply large deviations analysis:

$$E_f^s = \min_{\lambda \in [0,1], R} \left\{ \frac{\lambda}{1-\lambda} e(R) + \frac{1}{1-\lambda} E_+(\lambda R) \right\}$$

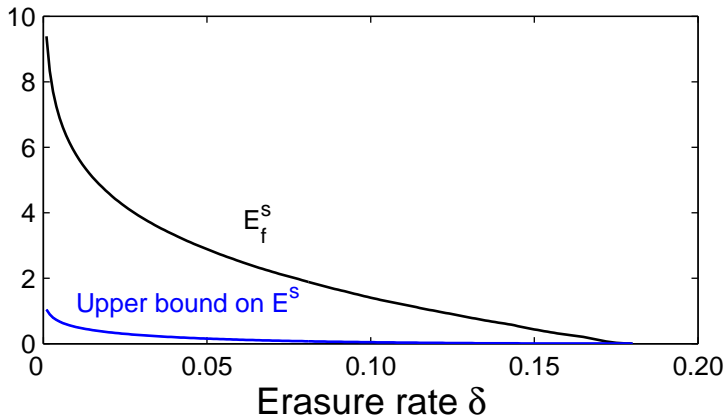
## $E_f^s$ feedback error exponents

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- Error exponents of a Bernoulli  $\frac{1}{4}$  source and binary erasure channels



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# Conclusions

$$\Pr(s_i \neq \hat{s}_i(i + \Delta)) \sim 2^{-\Delta E^s}$$

- Without channel feedback
  - ▶ A tighter lower bound with free punctuation
  - ▶ Queueing + randomized tree coding

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- Future directions
  - ▶ Eliminating or simulating “free punctuation”
  - ▶ Truly multiterminal bounding techniques