

Implicit Maximum Likelihood Estimation Berkelev UNIVERSITY OF CALIFORNIA

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Introduction

- Implicit probabilistic models:
 - $\mathbf{z} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$ $\mathbf{y} = T_{\theta}(\mathbf{z})$
- Challenge: Likelihood function cannot be expressed analytically or computed numerically.



 T_{θ}

У

Advantages

No More Mode Collapse/Dropping

- Why is this important? This allows control over recall.
- Otherwise better sample quality (precision) does not necessarily mean better modelling.
 - Wouldn't be able to tell apart the following cases:

- Question: How to train such models?
- Existing Approach: Generative adversarial nets (GANs)



Consequence: Unable to learn the data distribution.

Implicit Maximum Likelihood Estimation

• Can we maximize likelihood without computing likelihood?





• Overcomes all three problems of GANs:



Application: Multimodal Prediction

- Conditional setting:
 - $\mathbf{z} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$ $\mathbf{y} = T_{\theta}(\mathbf{x}, \mathbf{z})$
- Different samples for the same input image:

Select the nearest *sample* to each data point (NOT the nearest data point to each sample).

Pull selected samples towards corresponding data points.

$$\mathbf{x}_{1}, \dots, \mathbf{x}_{n}: \text{data points} \quad \tilde{\mathbf{x}}_{1}^{\theta}, \dots, \tilde{\mathbf{x}}_{m}^{\theta}: \text{i.i.d. samples}$$
$$\hat{\theta}_{\text{IMLE}} := \arg\min_{\theta} \mathbb{E}_{\tilde{\mathbf{x}}_{1}^{\theta}, \dots, \tilde{\mathbf{x}}_{m}^{\theta}} \left[\sum_{i=1}^{n} \min_{j \in [m]} \left\| \tilde{\mathbf{x}}_{j}^{\theta} - \mathbf{x}_{i} \right\|_{2}^{2} \right]$$

- Why? Maximize likelihood ⇔ High density at each data point \Leftrightarrow Samples likely to be near data points (Proof is in the paper)
- Difference from a GAN with a 1-nearest neighbour

Multimodal Super-Resolution



• Multimodal Image Synthesis from Semantic Layout



discriminator:



Push samples towards region containing real data.



not have a nearby sample.

References

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