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Jordan canonical form

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Let A be any complex $n \times n$ matrix. The expression det(sI - A) is a polynomial in s of degree n. It is called the *characteristic polynomial* of A. It is a *monic* polynomial, i.e. the coefficient of the highest degree term (s^n) is 1.

By the fundamental theorem of algebra, every polynomial with complex coefficients factors into degree one factors with complex coefficients. If the polynomial is monic, so are the factors, i.e each factor is of the form $(s - \lambda)$ for some complex number λ . These complex numbers are the *roots* of the polynomial. The roots of the characteristic polynomial of a matrix are called its *eigenvalues*.

In general, a polynomial can have repeated roots. Suppose det(sI - A) has d distinct roots $\lambda_1, \lambda_2, \ldots, \lambda_d$ having respective multiplicities a_1, a_2, \ldots, a_d , i.e.

$$\det(sI - A) = \prod_{i=1}^d (s - \lambda_i)^{a_i} \; .$$

 a_i is called the *algebraic multiplicity* of the eigenvalue λ_i . We have $\sum_{i=1}^d a_i = n$.

The eigenspace of A corresponding to the eigenvalue λ_i is the null space of the matrix $\lambda_i I - A$, denoted $\mathcal{N}(\lambda_i I - A)$. It is nontrivial, i.e. it has dimension at least 1, as can be checked by realizing that $\lambda_i I - A$ is a singular complex matrix, i.e. has determinant equal to zero, which in turn is equivalent to λ_i being a root of the characteristic polynomial of A, i.e. being an eigenvalue of A. The dimension of the null space of $\lambda_i I - A$, denoted g_i , is called the geometric multiplicity of the eigenvalue λ_i .

This handout will mention several facts without proof. Some of these facts may be new to you. If so, you may want to look up their proofs. You will find good treatments of this in most books on linear algebra (e.g. Strang) or abstract algebra (e.g. Hungerford or Jacobson). Another way to get intuition is to play around with several examples. You can do this quite easily by using MATLAB to do the calculations for you.

In general, for each eigenvalue λ_i , we have $g_i \leq a_i$, i.e. the dimension of the eigenspace of the eigenvalue at most equals its multiplicity as a root of the characteristic polynomial, and the inequality can be strict. One has

$$\mathcal{N}(\lambda_i I - A) \subseteq \mathcal{N}((\lambda_i I - A)^2) \subseteq \dots$$

Strict inclusion will hold till a certain stage, call it m_i , after which all the subspaces in this sequence will be equal, i.e. m_i is defined by

$$\mathcal{N}((\lambda_i I - A)^{m_i - 1}) \stackrel{\subseteq}{\neq} \mathcal{N}((\lambda_i I - A)^{m_i}) = \mathcal{N}((\lambda_i I - A)^{m_i + 1}) = \mathcal{N}((\lambda_i I - A)^{m_i + 2}) = \dots$$

The dimension of $\mathcal{N}((\lambda_i I - A)^{m_i})$ will equal a_i , the algebraic multiplicity of λ_i . $\mathcal{N}((\lambda_i I - A)^{m_i})$ is called the *generalized eigenspace* of the eigenvalue λ_i . Note that the generalized eigenspace of an eigenvalue equals its eigenspace precisely when the geometric multiplicity of the eigenvalue equals its algebraic multiplicity. In particular, this is always true if the algebraic multiplicity of the eigenvalue is 1, i.e., if it is a simple root of the characteristic polynomial. However, this condition is not necessary. For instance, each eigenvalue of a symmetric matrix has its geometric multiplicity as a root of the characteristic polynomial) irrespective of what its algebraic multiplicity is.

Every matrix A can be put in Jordan canonical form by a similarity transformation (change of basis). In fact, one can choose a basis b_{i1}, \ldots, b_{ia_i} for each generalized eigenspace $\mathcal{N}((\lambda_i I - A)^{m_i})$, $1 \leq i \leq d$, such that if U denotes the matrix

$$U = [b_{11} \dots b_{1a_1} b_{21} \dots b_{2a_2} \dots b_{d1} \dots b_{da_d}]$$

then one has $U^{-1}AU = J$, where J has the block diagonal form

$$J = \text{diag}(J_{11}, \dots, J_{1g_1}, J_{21}, \dots, J_{2g_2}, \dots, J_{d1}, \dots, J_{dg_d}) .$$

Here each J_{ij} for $1 \le j \le g_i$ is an $m_{ij} \times m_{ij}$ matrix of the form

$$J_{ij} = \begin{bmatrix} \lambda_i & 1 & 0 & \dots & 0 \\ 0 & \lambda_i & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 1 \\ 0 & 0 & 0 & \dots & \lambda_i \end{bmatrix}$$

Note that, for each $1 \leq i \leq d$,

$$a_i = \sum_{j=1}^{g_i} m_{ij} \; .$$

For each $1 \leq i \leq d$, one has $\max_j m_{ij} = m_i$, where m_i was defined above. The dimension of the eigenspace $\mathcal{N}(\lambda_i I - A)$ equals $\sum_{j=1}^{g_i} 1(m_{ij} \geq 1) = \sum_{j=1}^{g_i} 1 = g_i$, the dimension of $\mathcal{N}((\lambda_i I - A)^2)$ equals $\sum_{j=1}^{g_i} 1(m_{ij} \geq 1) + \sum_{j=1}^{g_i} 1(m_{ij} \geq 2)$ and so on, with the dimension of $\mathcal{N}((\lambda_i I - A)^{m_i})$ equaling

$$\sum_{j=1}^{g_i} 1(m_{ij} \ge 1) + \ldots + \sum_{j=1}^{g_i} 1(m_{ij} \ge m_i) = \sum_{j=1}^{g_i} m_{ij} = a_i \; .$$

Further, the columns $b_{i1}, b_{i(1+m_{i1})}, \ldots, b_{i(1+m_{i1}+\ldots+m_{i(g_i-1)})}$ (of which there are exactly g_i) form a basis for the eigenspace of λ_i .

Note that if we write

$$U^{-1} = \left[c_{11}^T \dots c_{1a_1}^T c_{21}^T \dots c_{2a_2}^T \dots c_{d1}^T \dots c_{da_d}^T\right]^T$$

then the rows c_{i1}, \ldots, c_{ia_i} are a basis for the left generalized eigenspace corresponding to the eigenvalue λ_i , and $c_{im_{i1}}, c_{i(m_{i1}+m_{i2})}, \ldots, c_{i(m_{i1}+\dots+m_{ig_i})}$ are a basis for the left eigenspace corresponding to the eigenvalue λ_i .

Since $A = UJU^{-1}$ we can now calculate the powers of A quite easily : $A^n = UJ^nU^{-1}$ and $J^n = \text{diag}(J_{11}^n, \ldots, J_{1g_1}^n, J_{21}^n, \ldots, J_{2g_2}^n, \ldots, J_{d1}^n, \ldots, J_{dg_d}^n)$. Here

$$J_{ij}^{n} = \begin{bmatrix} \lambda_{i}^{n} & \binom{n}{1} \lambda_{i}^{n-1} & \binom{n}{2} \lambda_{i}^{n-2} & \dots & \binom{n}{m_{ij}-1} \lambda_{i}^{n-m_{ij}+1} \\ 0 & \lambda_{i}^{n} & \binom{n}{1} \lambda_{i}^{n-1} & \dots & \binom{n}{m_{ij}-2} \lambda_{i}^{n-m_{ij}+2} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & \lambda_{i}^{n} \end{bmatrix} .$$

Check this !!