## **Taylor Series for Differential Equation Solvers' Local Error** Math. 128:

The *Taylor Series* of an infinitely differentiable vector-valued function y(t) of a scalar t is

 $v(t) = v(0) + t \cdot v'(0) + t^2 \cdot v''(0)/2 + t^3 \cdot v'''(0)/6 + t^4 \cdot v'''(0)/24 + \dots$ 

These derivatives can be computed for a solution of the Initial Value Problem

"  $y(0) = y_0$  is given, and y'(t) = f(y(t)) for all  $t \ge 0$ "

from the derivatives of the given vector-valued function f(y). In fact, from the *Chain Rule*, v' = f,  $v'' = f' \cdot f$ ,  $v''' = f'' \cdot f \cdot f + f'^2 \cdot f$ ,  $v'''' = f''' \cdot f \cdot f + 3f'' \cdot f' \cdot f \cdot f + f' \cdot f'' \cdot f \cdot f + f'^3 \cdot f$ , ... Then each derivative of y(t) can be evaluated at t = 0 by evaluating each derivative of f(y) at  $y = y(0) = y_0$ . Note that the higher derivatives of f are symmetric multilinear operators; for instance, f''(y) is a symmetric bilinear operator:  $f'' \cdot u \cdot v = f'' \cdot v \cdot u$  is a vector-valued linear function of each vector u and v separately. Because linear operators do not necessarily commute,  $f'' \cdot f' \cdot f \cdot f \neq f' \cdot f'' \cdot f \cdot f$  in general, though they are equal if y's vector space is onedimensional. If y's vector space is N-dimensional, then y and f can be represented by column vectors each with N components; f' by a matrix with N<sup>2</sup> components; f'' by an array with N<sup>3</sup> components of which at most  $(N+1)N^2/2$  can be distinct; f''' by an array of N<sup>4</sup> components .... Higher derivatives' arrays become huge when N is large.

Normally the Taylor series would be used to obtain y(t+h) from y(t) for any sufficiently small stepsize h:

 $y(t+h) = y(t) + h \cdot y'(t) + h^2 \cdot y''(t)/2 + h^3 \cdot y'''(t)/6 + h^4 \cdot y'''(t)/24 + \dots$ 

in which the derivatives dy(t+h)/dh etc. are computed at h = 0 from the same formulas y' = f,  $y'' = f' \cdot f$ ,  $y''' = f'' \cdot f \cdot f + f'^2 \cdot f$ ,  $y'''' = f''' \cdot f \cdot f + 3f'' \cdot f' \cdot f \cdot f + f' \cdot f'' \cdot f \cdot f + f'^3 \cdot f$ , ... as before except that now f(y) and its derivatives are computed at y = y(t).

A similar process generates a formal series for any one-step numerical method's formula that advances an approximate solution y = y(t) through one step h to Y = Y(t+h), but now we differentiate with respect to h instead of t to get

 $Y(t+h) = y + h \cdot Y' + h^2 \cdot Y''/2 + h^3 \cdot Y'''/6 + h^4 \cdot Y'''/24 + \dots$ 

in which y = y(t) and the derivatives Y' etc. are derivatives of Y(t+h) with respect to h evaluated at h = 0. These derivatives depend upon the numerical method's formula. For example, take the (implicit) Trapezoidal Rule  $Y = y + h \cdot (f(y) + f(Y))/2$ . Now, at t+h,  $V' - (f(v) + f(V))/2 + h \cdot f'(V) \cdot V'/2$ 

$$Y'' = f'(Y) \cdot Y' + h \cdot (f''(Y) \cdot Y' \cdot Y' + f'(Y) \cdot Y'')/2,$$

$$Y''' = 3f''(Y) \cdot Y' \cdot Y'/2 + f'(Y) \cdot Y''/2 + h \cdot (f'''(Y) \cdot Y' \cdot Y' + ...)/2 .$$
 etc

 $Y''' = 3f''(Y) \cdot Y' \cdot Y'/2 + f'(Y) \cdot Y''/2 + h \cdot (f'''(Y) \cdot Y' \cdot Y' \cdot Y' + \dots)/2, \text{ etc.}$ Here every instance of Y or its derivatives is evaluated at t+h. For the Taylor series we set h = 0 in the foregoing formulas and substitute for derivatives of Y in succession to get

$$Y' = f$$
,  $Y'' = f' \cdot f$ ,  $Y''' = (3f'' \cdot f + f'^2) \cdot f/2$ , ...

in which now the derivatives of Y are evaluated at t, and f and its derivatives are evaluated at y(t). Hence, the computed approximation

$$Y(t+h) = y(t) + h \cdot f + h^2 \cdot f' \cdot f/2 + h^3 \cdot (3f'' \cdot f + f'^2) \cdot f/12 + \dots$$

can be compared with the local solution

$$y(t+h) = y(t) + h \cdot f + h^2 \cdot f' \cdot f/2 + h^3 \cdot (f'' \cdot f + f'^2) \cdot f/6 + \dots$$

to reveal the 2nd-order Trapezoidal Rule's local truncation error

$$y(t+h) - Y(t+h) = h^3 \cdot (f'^2 - f'' \cdot f) \cdot f/12 + \dots$$

Another example is the (implicit) Midpoint Rule  $Y = y + h \cdot f((y+Y)/2)$ . At t+h,

$$\begin{split} \mathbf{Y'} &= f((\mathbf{y}+\mathbf{Y})/2) + \mathbf{h} \cdot f'((\mathbf{y}+\mathbf{Y})/2) \cdot \mathbf{Y'}/2 , \\ \mathbf{Y''} &= f'((\mathbf{y}+\mathbf{Y})/2) \cdot \mathbf{Y'} + \mathbf{h} \cdot (f''((\mathbf{y}+\mathbf{Y})/2) \cdot \mathbf{Y'} \cdot \mathbf{Y'}/4 + f'((\mathbf{y}+\mathbf{Y})/2) \cdot \mathbf{Y''}/2 ) , \\ \mathbf{Y'''} &= 3f''((\mathbf{y}+\mathbf{Y})/2) \cdot \mathbf{Y'} \cdot \mathbf{Y'}/4 + 3f'((\mathbf{y}+\mathbf{Y})/2) \cdot \mathbf{Y''}/2 + \mathbf{h} \cdot (f''' \dots) , \text{ etc.} \end{split}$$

Setting h = 0 and substituting for derivatives of Y in succession yields

Y' = f,  $Y'' = f' \cdot f$ ,  $Y''' = (3f'' \cdot f + 6f'^2) \cdot f/4$ , ...

in which now the derivatives of Y are evaluated at t, and f and its derivatives are evaluated at y(t). Hence, by comparison with the Taylor series for y(t+h) we find the 2nd-order Midpoint Rule's local truncation error to be

$$y(t+h) - Y(t+h) = h^3 \cdot (f'' \cdot f - 2f'^2) \cdot f/24 + \dots$$

The foregoing manipulations are tedious enough that only a computerized algebra system should perform them. However, programming *Maple* or *Mathematica* or *Derive* to perform them has been more difficult than it should be. At least some of the difficulty arises, I think, because these languages disallow declaration of a variable's linguistic *Type*. Besides the derivatives' non-commutative partially associative multiplication, their multi-linear symmetry has to be taken into account in order to achieve correct simplifications of expressions like the fifth derivative

$$y^{v} = f^{"} \cdot f \cdot f \cdot f \cdot f + 6f^{"} \cdot f' \cdot f \cdot f \cdot f + 4f^{"} \cdot f' \cdot f \cdot f + 4f^{"} \cdot f'^{2} \cdot f \cdot f + 4f^{"} \cdot f'^{2} \cdot f \cdot f + 3f^{"} \cdot f' \cdot f \cdot f + 5f^{-2} \cdot f'' \cdot f \cdot f + f'^{4} \cdot f \cdot f + 3f'' \cdot f' \cdot f \cdot f + 5f^{-2} \cdot f'' \cdot f \cdot f + f'^{4} \cdot f \cdot f + 5f^{-2} \cdot f'' \cdot f \cdot f + 5f^{-2} \cdot$$

The foregoing *formal* (because their convergence is undetermined) Taylor series expansions do not reveal an important property possessed by the computed solution Y of the Initial Value Problem when it is obtained from a *Reflexive* formula, which is a formula in which Y(t+h) and y(t) are merely swapped when the sign of h is reversed. The Midpoint and Trapezoidal Rules' formulas are reflexive. The composition of T/h steps of a reflexive formula to approximate the true solution y(T) at a fixed T, but using any sufficiently small stepsize h so long as T/h is an integer, can be proved to produce a computed approximation Y(T) that depends upon h and differs from y(T) by an error

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$$y(T) - Y(T) = c_2h^2 + c_4h^4 + c_6h^6 + \dots$$

whose formal expansion in powers of h contains only even powers. The expansion need not converge for any h > 0; instead it is an *Asymptotic* expansion whose behavior is conveyed by its first few terms ever more accurately as  $h \rightarrow 0$ . Recomputations of Y(T) with diminishing stepsizes h, h/2, h/4, h/8, ... provides a sequence to which *Richardson's Extrapolation* can be applied, as in *Romberg* integration, to achieve what amounts to higher-order convergence.