

Experts/Zero-Sum Games Equilibrium.

Experts/Zero-Sum Games Equilibrium. Boosting and Experts. Experts/Zero-Sum Games Equilibrium.

Boosting and Experts.

Routing and Experts.

#### Two person zero sum games. $m \times n$ payoff matrix A.

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$$p(x,y) = x^t A y$$

That is,

$$\sum_{i} x_{i} \left( \sum_{j} a_{i,j} y_{j} \right) = \sum_{j} \left( \sum_{i} x_{i} a_{i,j} \right) y_{j}$$

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(No better column strategy, no better row strategy.)

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No row is better:

$$\min_i A^{(i)} \cdot y = (x^*)^t A y^*.$$

No column is better:  $\max_{j} (A^{t})^{(j)} \cdot x = (x^{*})^{t} A y^{*}.$ 

 ${}^{1}A^{(i)}$  is *i*th row.

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Find *y*, where best row is not too low..

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Strong Duality: There is an equilibrium point!

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**Strong Duality:** There is an equilibrium point! and R = C!
### Duality.

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Doesn't matter who plays first!

Later.

Later. Still later...

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Aproximate equilibrium ...

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 $C(x) = \max_{y} x^{t} A y$  $R(y) = \min_{x} x^{t} A y$ 

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 $C(x) = \max_{y} x^{t} A y$   $R(y) = \min_{x} x^{t} A y$ Always:  $R(y) \le C(x)$ 

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Approximate Equilibrium:  $C(x) - R(y) \le \varepsilon$ .

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With  $R(y) \le C(x)$ 

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Aproximate equilibrium ...

 $C(x) = \max_{v} x^{t} A v$  $R(y) = \min_{x} x^{t} A y$ Always:  $R(y) \leq C(x)$ Strategy pair: (x, y)Equilibrium: (x, y) $R(y) = C(x) \rightarrow C(x) - R(y) = 0.$ Approximate Equilibrium:  $C(x) - R(y) \le \varepsilon$ . With R(y) < C(x) $\rightarrow$  "Response y to x is within  $\varepsilon$  of best response"

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Not hard. Even easy. Still, head scratching happens.

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Experts Framework: *n* Experts, *T* days, *L*\* -total loss.

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Multiplicative Weights Method yields loss *L* where

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Multiplicative Weights Method yields loss L where

$$L \leq (1+\varepsilon)L^* + \frac{\log n}{\varepsilon}$$

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**Claim:**  $(x^*, y)^*$  are  $2\varepsilon$ -optimal for matrix *A*.

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 $x_t$  minimizes the best column response is chosen. Clearly good for row. column best response is at least what it is against  $x_t$ .

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column best response is at least what it is against  $x_t$ . Total loss, L is at least column payoff.

Assume: A has payoffs in [0,1].

For  $T = \frac{\log n}{\varepsilon^2}$  days:

1) *m* pure row strategies are experts. Use multiplicative weights, produce row distribution. Let  $x_t$  be distribution (row strategy)  $x_t$  on day *t*.

2) Each day, adversary plays best column response to  $x_t$ . Choose column of A that maximizes row's expected loss. Let  $y_t$  be indicator vector for this column.

Let  $y^* = \frac{1}{T} \sum_t y_t$  and  $x^* = \operatorname{argmin}_{x_t} x_t A y_t$ .

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Multiplicative Weights:

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Multiplicative Weights:  $L \leq (1 + \varepsilon)L^* + \frac{\ln n}{\varepsilon}$ 

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 $TC(x^*) \leq (1+\varepsilon)TR(y^*) + \frac{\ln n}{\varepsilon} \to C(x^*) \leq (1+\varepsilon)R(y^*) + \frac{\ln n}{\varepsilon T}$ 

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$$TC(x^*) \leq (1+\varepsilon)TR(y^*) + \frac{\ln n}{\varepsilon} \to C(x^*) \leq (1+\varepsilon)R(y^*) + \frac{\ln n}{\varepsilon T} \\ \to C(x^*) - R(y^*) \leq \varepsilon R(y^*) + \frac{\ln n}{\varepsilon T}.$$

 $T=rac{\ln n}{arepsilon^2},\ R(y^*)\leq 1$ 

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#### Approximate Equilibrium: notes!

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Column payoff:  $C(x^*) = \max_y x^* Ay$ . Let  $y_r$  be best response to  $C(x^*)$ .

Experts:  $x_t$  is strategy on day t,  $y_t$  is best column against  $x_t$ .

Let  $x^* = \frac{1}{T} \sum_t x_t$  and  $y^* = \frac{1}{T} \sum_t y_t$ .

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Column payoff:  $C(x^*) = \max_y x^* Ay$ . Let  $y_r$  be best response to  $C(x^*)$ . Day  $t, y_t$  best response to  $x_t \rightarrow x_t Ay_t \ge x_t Ay_r$ .

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Day t, y_t best response to x_t \rightarrow x_t Ay_t \ge x_t Ay_r.
Algorithm loss: \sum_t x_t Ay_t \ge \sum_t x_t Ay_r
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Best expert:  $L^*$ - best row against all the columns played.

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Experts:  $x_t$  is strategy on day t,  $y_t$  is best column against  $x_t$ .

Let  $x^* = \frac{1}{T} \sum_t x_t$  and  $y^* = \frac{1}{T} \sum_t y_t$ .

**Claim:**  $(x^*, y)^*$  are 2 $\varepsilon$ -optimal for matrix *A*.

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Column payoff: C(x^*) = \max_y x^* Ay.
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 $TC(x^*) \leq (1+\varepsilon)TR(y^*) + \frac{\ln n}{\varepsilon}$ 

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"In practice."

Learning just a bit.

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Example: set of labelled points, find hyperplane that separates.

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Looks hard.

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Get 1/2 on correct side?

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Get 1/2 on correct side? Easy. Arbitrary line.

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Get 1/2 on correct side? Easy. Arbitrary line. And Scan.

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Not really important but ...

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Boosting: use a weak learner to produce strong learner.



Given a weak learning method (produce ok hypotheses.)

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**Multiplicative Weights!** 

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Multiplicative Weights!

The endpoint to a line of research.

# **Experts Picture**
Experts are points.

Experts are points. "Adversary" weak learner.

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In limit, whole distribution becomes such point.

Intuition 1: Each point classified correctly independently in each round with probability  $\frac{1}{2} + \varepsilon$ .

After enough rounds, majority rule correct for almost all points. Intuition 2:

Say some point classified correctly  $\leq 1/2$  of time.

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This subset will be classified correctly with probability  $1/2 + \varepsilon$ .

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Set  $\varepsilon = \gamma$ , take logs.

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not so weak after all.

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Weak learner: random Wow. That's weak.

#### Better weak learner?

Hyperplane that separates weighted average of +/- points?

Hyperplane that separates weighted average of +/- points? Change loss a bit, and get better results.

Given: G = (V, E). Given  $(s_1, t_1) \dots (s_k, t_k)$ . Row: choose routing of all paths. Column: choose edge. Row pays if column chooses edge on any path.

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Defense: Toll: maximize shortest path under tolls.

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Runtime only dependent on m and T (number of days.)

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$$\begin{split} & G \leq C^* T - \text{each day, gain is average congestion} \leq C^* \\ & \text{since each day cost is toll solution which is at most } C^* \\ & C^* T \geq c_{max} T(1-\varepsilon) - \frac{k \log n}{\varepsilon} \\ & \text{For } T = \frac{k \log n}{\varepsilon^2} \\ & \rightarrow C^* \frac{1}{1-\varepsilon} + \varepsilon \geq c_{max} \text{ plus } \frac{1}{1-\varepsilon} \leq 1+\varepsilon \end{split}$$

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Runtime: O(km) to route in each step.

#### Better setup.

# Runtime: O(km) to route in each step. $O(k \log n(\frac{1}{\epsilon^2}))$ steps

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#### Better setup.

# Runtime: O(km) to route in each step. $O(k \log n(\frac{1}{\epsilon^2}))$ steps $\rightarrow O(k^2 m \log n)$ to get a constant approximation.

Homework:  $O(km \log n)$  algorithm.

Did we solve path routing?

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No!

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No! Average of *T* routings.

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Homework 2. Problem 1.

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Homework 2. Problem 1.

Decent solution to path routing problem?

For each  $s_i$ ,  $t_i$ , choose path  $p_i$  with probability  $f(p_i)$ .

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Congestion c(e) edge rounds to  $\tilde{c}(e)$ .

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used by paths  $p_1, \ldots, p_m$ .

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Edge *e*. used by paths  $p_1, \ldots, p_m$ . Let  $X_i = 1$ , if path  $p_i$  is chosen.

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Concentration (law of large numbers)

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Concentration (law of large numbers) c(e) is relatively large  $(\Omega(\log n))$ 

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Concentration (law of large numbers)

c(e) is relatively large  $(\Omega(\log n))$  $\rightarrow \tilde{c}(e) \approx c(e)$ .

Concentration results?

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Concentration results? later.
See you on Tuesday.