### Welcome back.

Projects comments available on Glookup! Turn in homework! I am away April 15-20. Midterm out when I get back. Few days takehome. Shiftable. Have handle on projects before that. Progress report due Monday.

### Gaussians

Population 1: Gaussion with mean  $\mu_1 \in \mathbb{R}^d$ , std deviation  $\sigma$  in each dim. Population 2: Gaussion with mean  $\mu_2 \in R^d$ , std deviation  $\sigma$  in each dim. Difference between humans  $\sigma$  per snp. Difference between populations  $\varepsilon$  per snp. How many snps to collect to determine population for individual x? x in population 1.  $E[(x - \mu_1)^2] = d\sigma^2$  $E[(x-\mu_2)^2] \ge (d-1)\sigma^2 + (\mu_1 - \mu_2)^2.$ If  $(\mu_1 - \mu_2)^2 = d\varepsilon^2 >> \sigma^2$ , then different.  $\rightarrow$  take  $d >> \sigma^2/\epsilon^2$ Variance of estimator? Roughly  $d\sigma^4$ . Signal is difference between expecations. roughly  $d\varepsilon^2$ Signal >> Noise.  $\leftrightarrow d\varepsilon^2 >> \sqrt{d}\sigma^2$ . No solution -4/-4

# Two populations.

#### DNA data:

human1: A  $\cdots$  C  $\cdots$  T  $\cdots$  A human2: C  $\cdots$  C  $\cdots$  A  $\cdots$  T human3: A  $\cdots$  G  $\cdots$  T  $\cdots$  T Single Nucleotide Polymorphism. Same population? Model: same populution breeds. Population 1: snp 843: Pr[A] = .4 , Pr[T] = .6 Population 2: snp 843: Pr[A] = .6 , Pr[T] = .4 Individual:  $x_1, x_2, x_3..., x_n$ . Which population? Comment: snps could be movie preferences, populations could be types.

E.g., republican/democrat, shopper/saver.

### Projection

Population 1: Gaussion with mean  $\mu_1 \in \mathbb{R}^d$ , variance  $\sigma$  in each dim. Population 2: Gaussion with mean  $\mu_2 \in \mathbb{R}^d$ , variance  $\sigma$  in each dim.

Difference between humans  $\sigma$  per snp. Difference between populations  $\varepsilon$  per snp. Project x onto unit vector v in direction  $\mu_2 - \mu_1$ .  $E[((x - \mu_1) \cdot v)^2] = 0$  if x is population 1.  $E[((x - \mu_2) \cdot v)^2] \ge (\mu_1 - \mu_2)^2$  if x is population 2. Std deviation is  $\sigma^2!$  versus  $\sqrt{d}\sigma^2!$ No loss in signal!  $d\varepsilon^2 >> \sigma^2$ .  $\rightarrow d >> \sigma^2/\varepsilon^2$ Versus  $d >> \sigma^4/\varepsilon^4$ .

A quadratic difference in amount of data!

#### Which population?

Population 1: snp 843: Pr[A] = .4, Pr[T] = .6Population 2: snp 843: Pr[A] = .6, Pr[T] = .4Individual:  $x_1, x_2, x_3..., x_n$ .

Population 1: snp *i*:  $Pr[x_i = 1] = p_i^{(1)}$ Population 2: snp *i*:  $Pr[x_i = 0] = p_i^{(2)}$ 

#### Simpler Calculation:

Population 1: Gaussion with mean  $\mu_1 \in R^d$ , variance  $\sigma$  in each dim. Population 2: Gaussion with mean  $\mu_2 \in R^d$ , variance  $\sigma$  in each dim.



### Don't know much about...

Don't know  $\mu_1$  or  $\mu_2$ ?

### Without the means?

Sample of *n* people. Some (say half) from population 1, some from population 2.

Which are which?

#### **Near Neighbors Approach**

Compute Euclidean distance squared. Cluster using threshold.

Signal  $E[d(x_1, x_2)] - E[d(x_1, y_1)]$ should be larger than noise in d(x, y)Where *x*'s from one population, *y*'s from other.

Signal is proportional  $d\varepsilon^2$ .

Noise is proportional to  $\sqrt{d}\sigma^2$ .

 $d >> \sigma^4 / \varepsilon^4 \longrightarrow$  same type people closer to each other.  $d >> (\sigma^4 / \varepsilon^4) \log n$  suffices for threshold clustering.

log *n* factor for union bound over  $\binom{n}{2}$  pairs.

Best one can do?

# PCA calculation.

Matrix *A* where rows are points. First eigenvector of  $B = A^T A$  is maximum variance direction. *Av* are projections onto *v*.  $vBv = (vA)^T (Av)$  is  $\sum_x (x \cdot v)^2$ .

First eigenvector, v, of B maximizes  $x^T B x$ .

 $Bv = \lambda v$  for maximum  $\lambda$ .  $\rightarrow vBv = \lambda$  for unit v.

Eigenvectors form orthonormal basis.

Any other vector av + x,  $x \cdot v = 0$ x is composed of possibly smaller eigenvalue vectors.

 $\rightarrow vBv \ge (av+x)B(av+x)$  for unit v, av+x.

### Principal components analysis. Remember Projection!



Don't know  $\mu_1$  or  $\mu_2$ ?

Principal component analysis: Find direction, *v*, of maximum variance. Maximize  $\sum (x \cdot v)^2$  (zero center the points) Recall:  $(x \cdot v)^2$  could determine population. Typical direction variance.  $n\sigma^2$ . Direction along  $\mu_1 - \mu_2$ ,  $\propto n(\mu_1 - \mu_2)^2$ .  $\propto nd\epsilon^2$ . Need  $d >> \sigma^2/\epsilon^2$  at least. When will PCA pick correct direction with good probability? Union bound over directions. How many directions? Infinity and beyond!

# Computing eigenvalues.

Power method: Choose random *x*. Repeat: Let x = Bx. Scale *x* to unit vector.

 $x=a_1v_1+a_2v_2+\cdots$ 

 $x_t \propto B^t x = a_1 \lambda_1^t v_1 + a_2 \lambda_2^t v_2 + \cdots$ Mostly  $v_1$  after a while since  $\lambda_1^t >> \lambda_2^t$ .

Cluster Algorithm: Choose random partition. Repeat: Compute means of partition. Project, cluster.

Choose random +1/-1 vector. Multiply by  $A^{T}$  (direction between means), multiply by A (project points), cluster (round to +1/-1 vector.)

Sort of repeatedly multiplying by  $AA^{T}$ . Power method.

#### Nets

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"δ - Net".

Set 𝔅 of directions

where all others, ν, are close to x \in 𝔅.

x \cdot v \ge 1 - \delta.

δ- Net:

[\cdots, i\delta/d, \cdots] integers i \in [-d/\delta, d\delta].

Total of N \propto \left(\frac{d}{\delta}\right)^{O(d)} vectors in net.

Signal >> Noise times log N = O(d \log \frac{d}{\delta}) to isolate direction.

log N is due to union bound over vectors in net.
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Signal (exp. projection):  $\propto nd\epsilon^2$ . Noise (std dev.):  $\sqrt{n\sigma^2}$ .

#### $nd >> (\sigma^4/\varepsilon^4)\log d$ and $d >> \sigma^2/\varepsilon^2$ works.

Nearest neighbor works with very high  $d > \sigma^4 / \varepsilon^4$ .

PCA can reduce *d* to "knowing centers" case, with reasonable number of sample points.

# Sum up.

Clustering mixture of gaussians. Near Neighbor works with sufficient data. Projection onto subspace of means is better. Principal compent analysis can find subspace of means. Power method computes principal component.

Generic clustering algorithm is rounded version of power method.

See you on Thursday.