# ON COMPACT CODES FOR Spatially Pooled Features

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## **1. SUMMARY**

- The learning community has been in favor of feature extraction pipelines that use feedfor-ward and over-complete representations.
- We link such pipeline with the Nyström sampling view to analyze the effect of the dictionary size (over-completeness) on the final classification performance.
- We derived a bound that predicts the performance of large codebook sizes with smaller ex-

## 4. FEATURE ENCODING

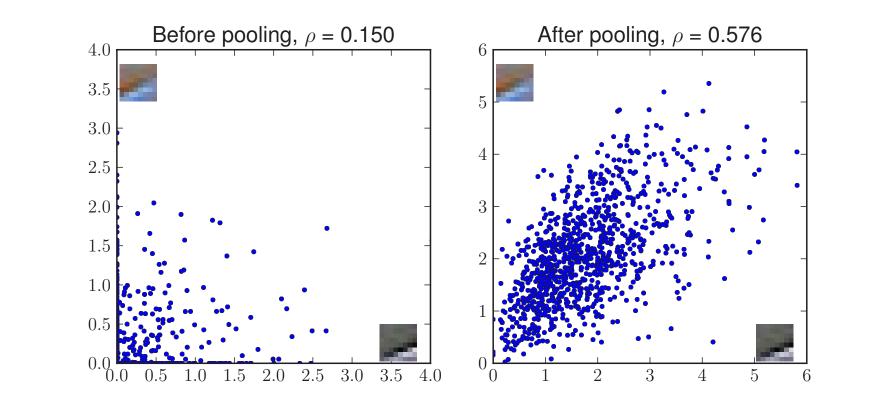
• Consider common pipelines in feature coding, e.g. rectified linear units (ReLU) to encode feature x with dictionary D:

 $\mathbf{c}(\mathbf{x}) = \max(0, \mathbf{x}^\top \mathbf{D})$ 

- Suppose we take D = X (all possible features) to have the best local coding so
  - $\mathbf{C} = \max(0, \mathbf{X}^{\top} \mathbf{X})$

# 6. POOLING-INVARIANT DICT LE

- Image Feature extraction almost always involve more than encoding.
- Conventional unsupervised methods focus on patch-based dictionary learning [Coates et al. ICML11], but pooling adds complications to the statistics of obtained features:





periments.

• Such a view leads to novel algorithms with complex feature extraction pipelines with efficient, scalable clustering algorithms.

## 2. BACKGROUND

Vision:

- Simple clustering methods are effective in dictionary learning in single-layer networks [Coates et al. ICML11].
- Deeper models are built on layers of feedforward encoding methods.

#### Speech:

- Acoustic modeling was one of the first adopters to feedforward networks, but over-complete representations were not explored until recently.
- Adding more layers of coding is also helpful to achieve better modeling [Vinyals et al, IS13].

which defines a linear kernel

 $\mathbf{K} = \mathbf{C}\mathbf{C}^{ op}$ 

But we need a compact codebook!

• Applying Nyström method to **C** (instead of **K**) we obtain

 $\mathbf{C}' \approx \mathbf{C} = \mathbf{E}\mathbf{W}^{+}\mathbf{E}^{\top}, \text{ and}$  $\mathbf{K}' \approx \mathbf{K} = \mathbf{C}'\mathbf{C}'^{\top} = \mathbf{E}\mathbf{W}^{+}\mathbf{E}^{\top}\mathbf{E}\mathbf{W}^{+}\mathbf{E}^{\top}$  $= \mathbf{E}\mathbf{A}\mathbf{E}^{\top}.$ 

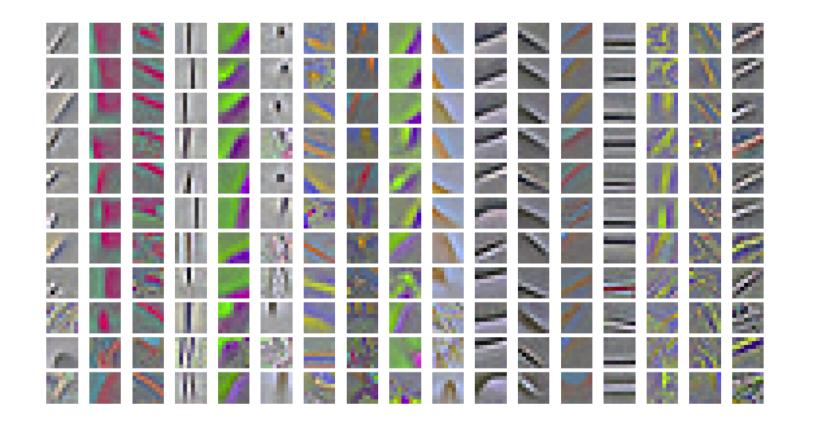
# 5. SIZE MATTERS

- We explain the good performance of codebooks learned by K-means [Coates et al. ICML11] or even randomly selected patches.
  - Using **E** is equivalent to using  $\mathbf{D} = RP$  assuming  $\mathbf{\Lambda} = \mathbf{I}$ .
  - Whitening makes  $\Lambda$  more diagonal.

- The Nyström sampling view suggests efficient ways to learn pooling-invariant dictionaries.
- We used a two-stage clustering algorithm to learn such a dictionary:
  - 1. an overshooting dictionary with patchbased K-means;
  - reducing the dictionary with affinity propagation (using covariance of pooled outputs as similarities).

## 6. RESULTS

• Learned codes (first row) and pruned codes (codes below):



# **3. THE NYSTRÖM METHOD**

Let C be an  $n \times n$  PSD matrix. The Nyström method defines:

 $\mathbf{C}' = \mathbf{E}\mathbf{W}^+\mathbf{E}^\top,$ 

where **E** is a  $n \times k$  matrix with columns randomly sampled from **C**:

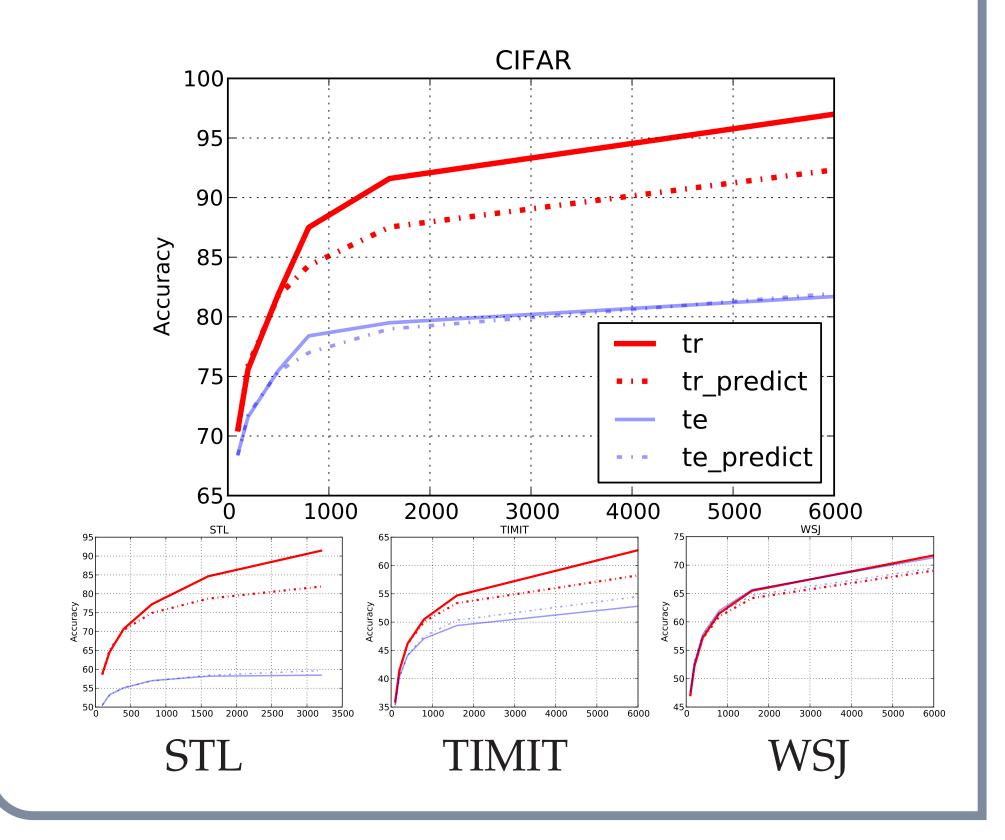
 $\mathbf{E} = \left( \begin{array}{cccc} | & | & | \\ \mathbf{c}_{\pi(1)} & \mathbf{c}_{\pi(2)} & \cdots & \mathbf{c}_{\pi(k)} \\ | & | & | \end{array} \right),$ 

and **W** is the square  $k \times k$  matrix by picking the same k columns and k rows from **C**.

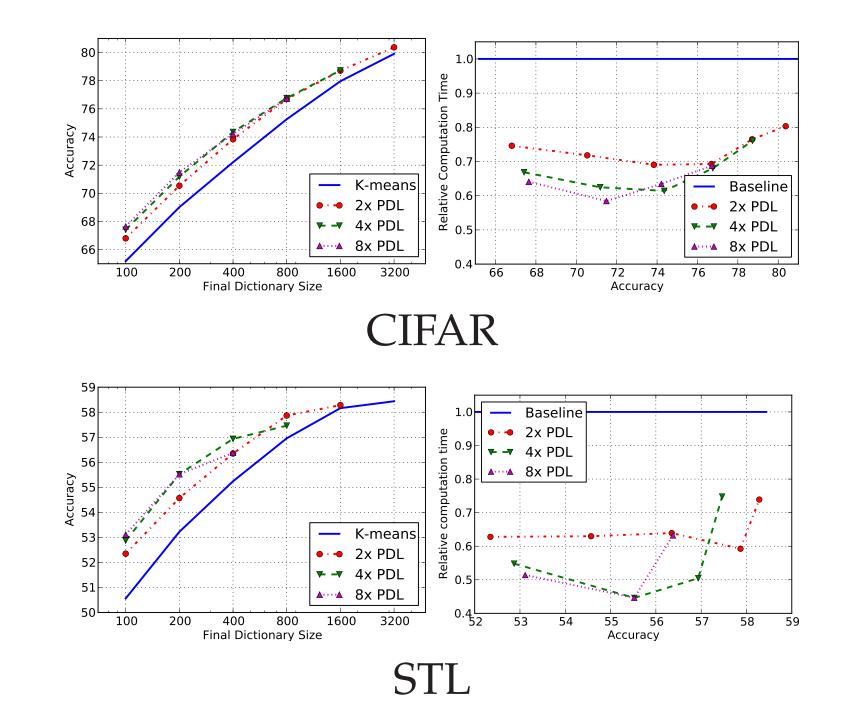
The matrix  $\mathbf{C}'$  is a good approximation to  $\mathbf{C}$  and the error is bounded by:

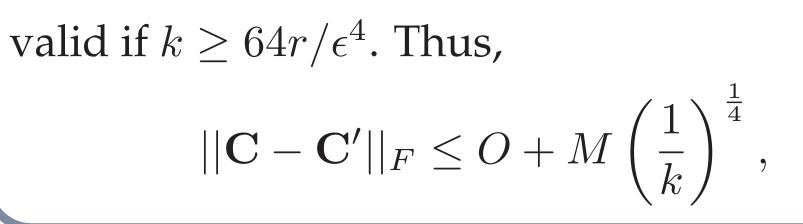
 $||\mathbf{C} - \mathbf{C}'||_F \le ||\mathbf{C} - \mathbf{C}_r||_F + \epsilon \max(n\mathbf{C}_{ii}),$ 

- We can bound the error in accuracy as a function of dictionary size.
  - The bound on K' is in the same form as that on C'.
  - Overall classification accuracy is (approximately) proportional to  $||\mathbf{K} - \mathbf{K}'||_F$ .
- On various datasets, larger codebook sizes exhibit diminishing returns, with our method giving a good estimation of the accuracy.



 Accuracy gain under fixed codebook sizes (left) and speedup under fixed accuracies (right):





• (Note that the method is purely unsupervised.)

### 7. REFERENCES

- O. Vinyals, Y. Jia, T. Darrell. Why Size Matters: Feature Coding as Nystrom Sampling. ICLR 2013.
- A. Coates, A. Ng. The Importance of Encoding versus Training with Sparse Coding and Vector Quantization. ICML 2011.
- O. Vinyals, L. Deng. Are Sparse Representations Rich Enough for Acoustic Modeling?. Interspeech 2012